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UNIVERSITY**

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# CSE 5525: Foundations of Speech and Language Processing

## Recurrent Neural Networks

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Many thanks to Prof. Greg Durrett @ UT Austin for sharing his slides.

# This Lecture

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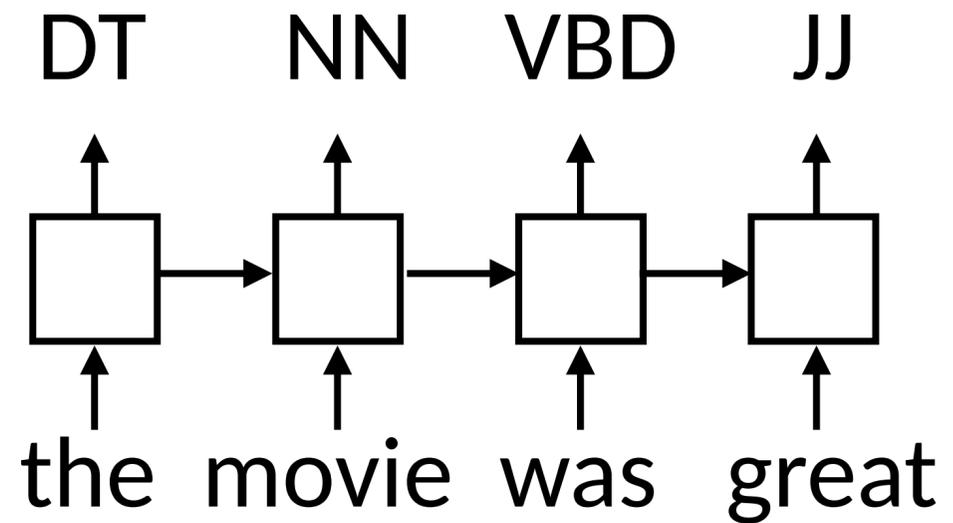
- ▶ Recurrent neural networks
- ▶ Vanishing gradient problem
- ▶ LSTMs / GRUs
- ▶ Applications / visualizations

# RNN Basics

# RNN Uses

Modeling sequential data

- ▶ Transducer: make some prediction for each element in a sequence

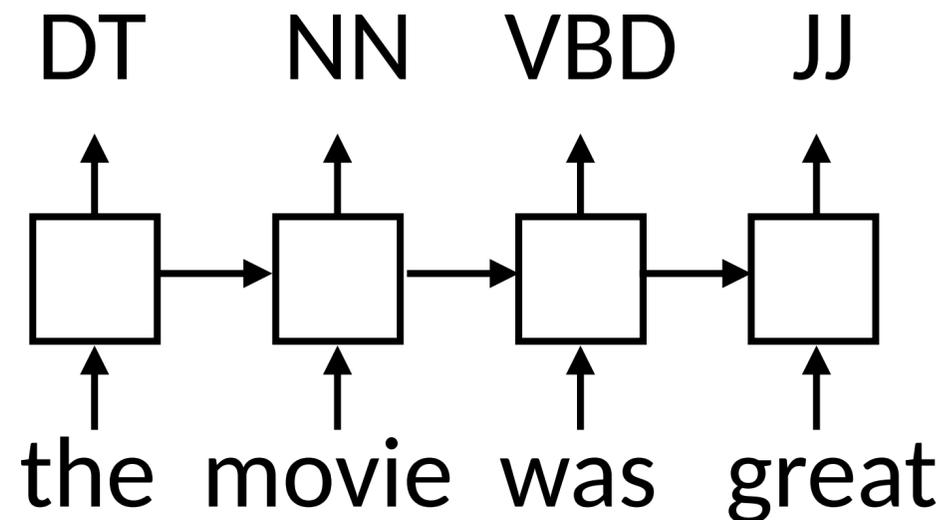


output  $y$  = score for each tag, then softmax

# RNN Uses

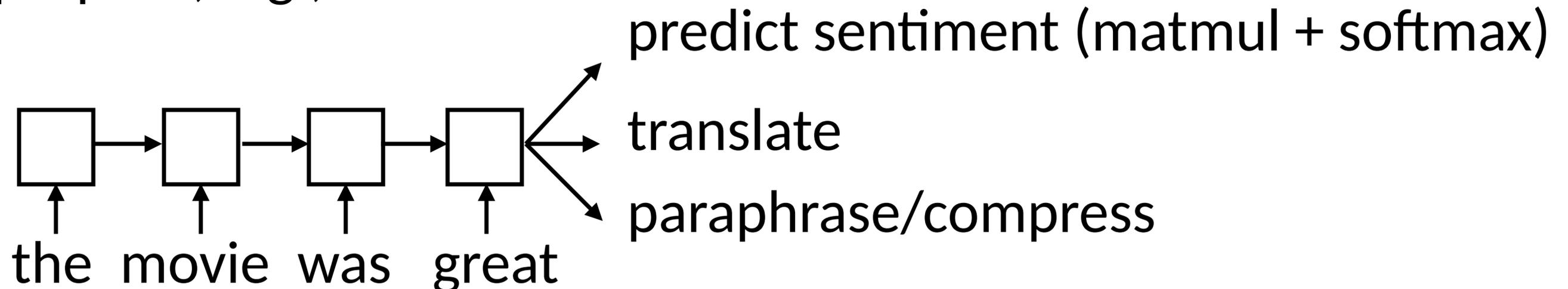
Modeling sequential data

- ▶ Transducer: make some prediction for each element in a sequence

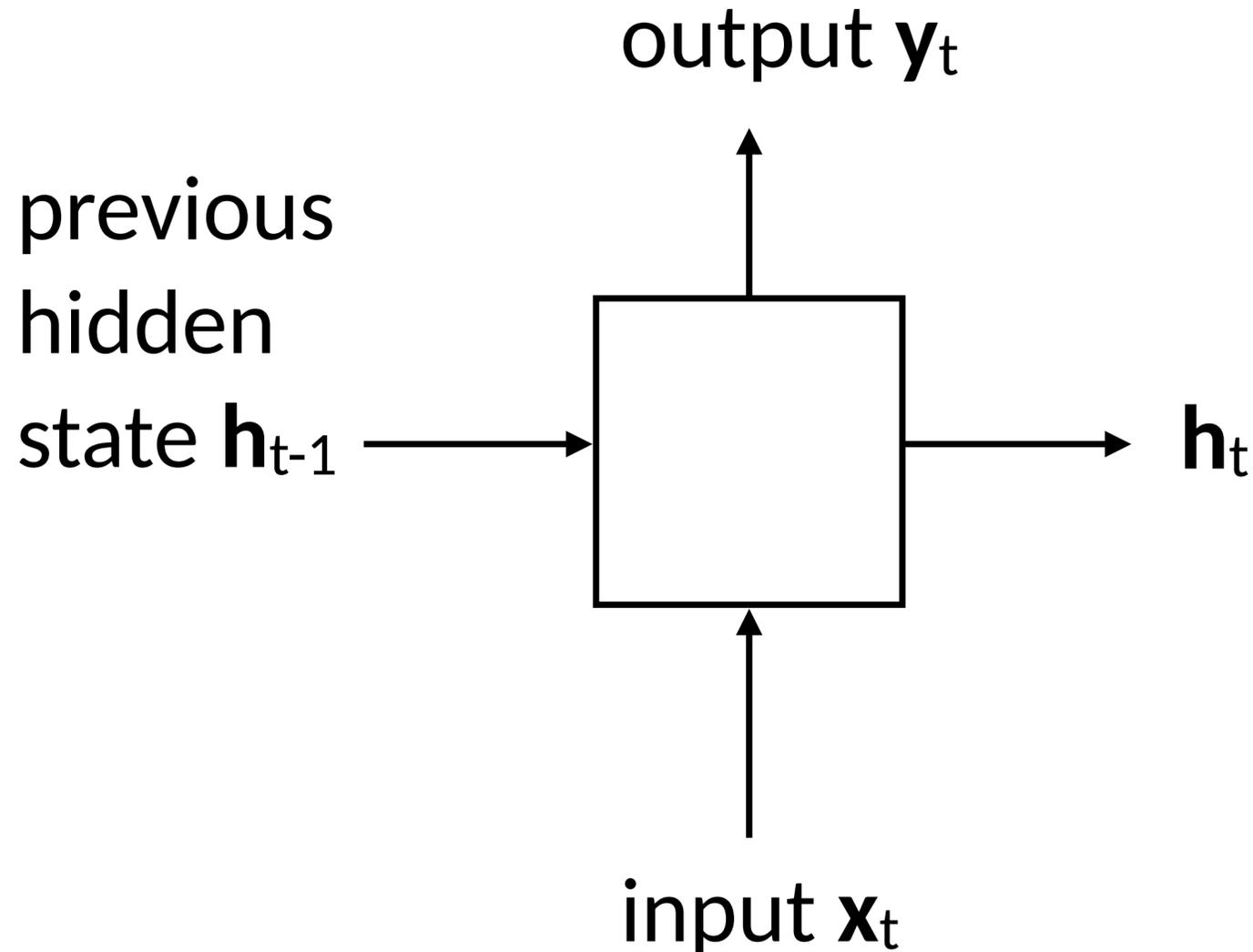


output  $y$  = score for each tag, then softmax

- ▶ Encoder: encode a sequence into a fixed-sized vector and use that for some purpose, e.g.,



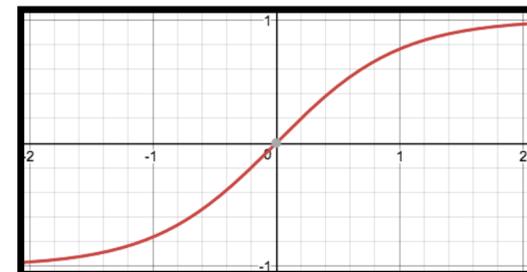
# Elman Networks (Simple Recurrent Networks)



- ▶ 1. Updates hidden state based on input and previous hidden state

$$\mathbf{h}_t = \tanh(W\mathbf{x}_t + V\mathbf{h}_{t-1} + \mathbf{b}_h)$$

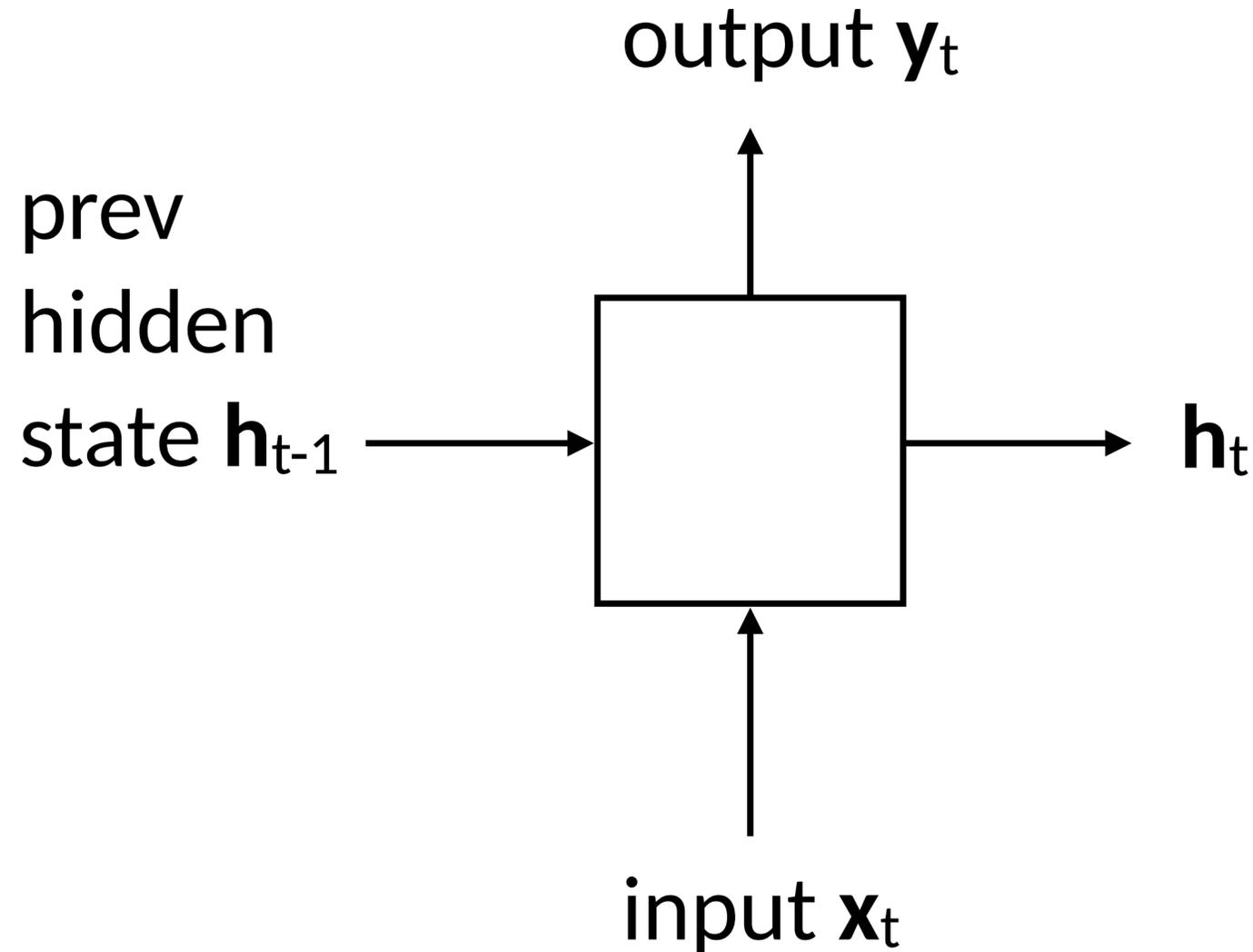
$$\tanh x = \frac{\sinh x}{\cosh x} = \frac{e^x - e^{-x}}{e^x + e^{-x}} = \frac{e^{2x} - 1}{e^{2x} + 1}$$



- ▶ Long history! (invented in the late 1980s)

Elman (1990)

# Elman Networks



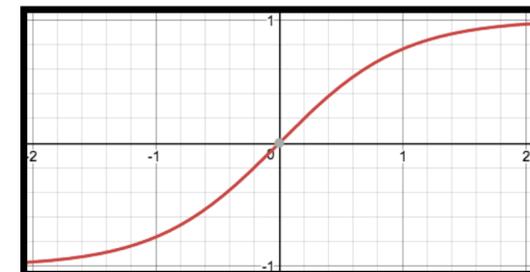
- ▶ 1. Updates hidden state based on input and previous hidden state

$$\mathbf{h}_t = \tanh(W\mathbf{x}_t + V\mathbf{h}_{t-1} + \mathbf{b}_h)$$

- ▶ 2. Computes output from hidden state

$$\mathbf{y}_t = \tanh(U\mathbf{h}_t + \mathbf{b}_y)$$

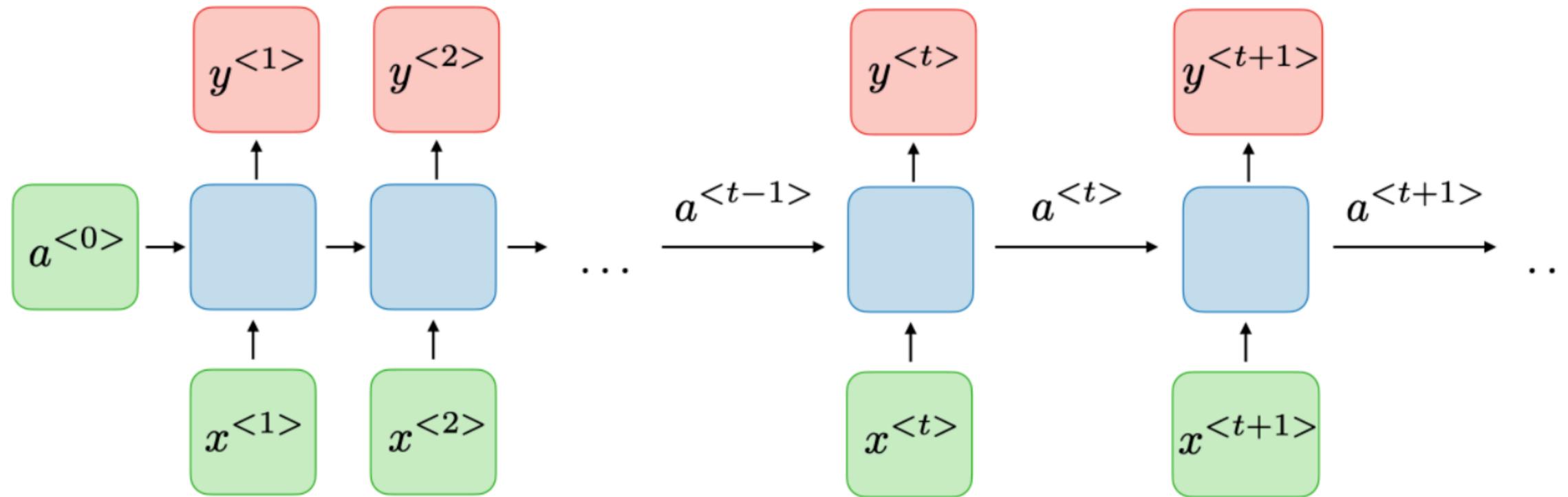
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Elman (1990)

# Elman Networks (Simple Recurrent Networks)



$$a^{<t>} = g_1(W_{aa}a^{<t-1>} + W_{ax}x^{<t>} + b_a)$$

and

$$y^{<t>} = g_2(W_{ya}a^{<t>} + b_y)$$

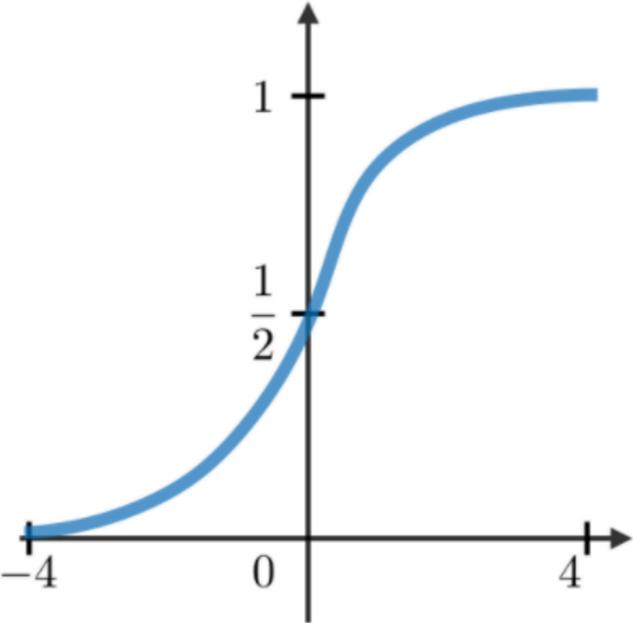
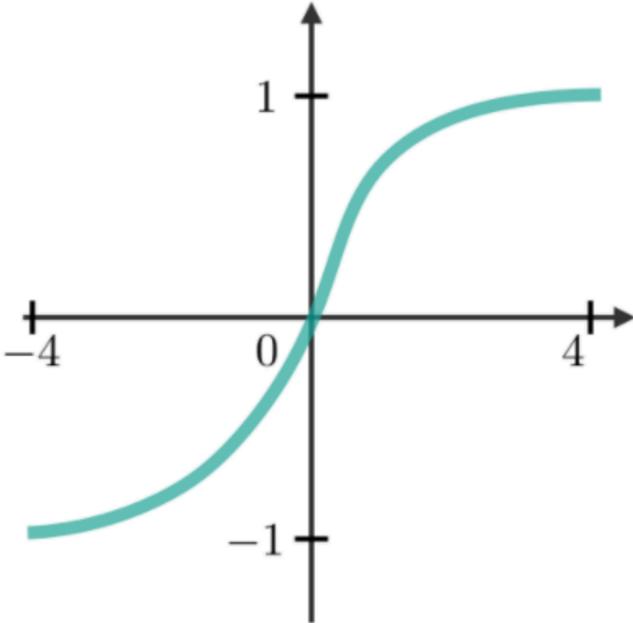
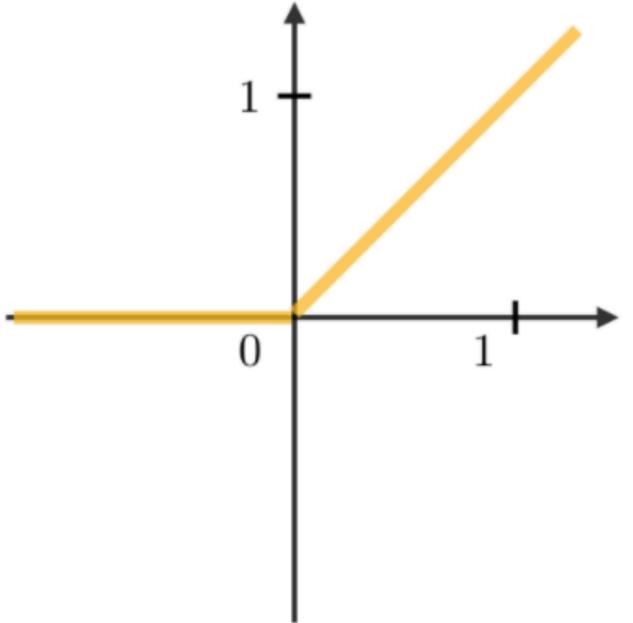
$W_{ax}, W_{aa}, W_{ya}, b_a, b_y$  are coefficients that are shared temporally

Same as previous slides, but we use  $a$  as hidden state

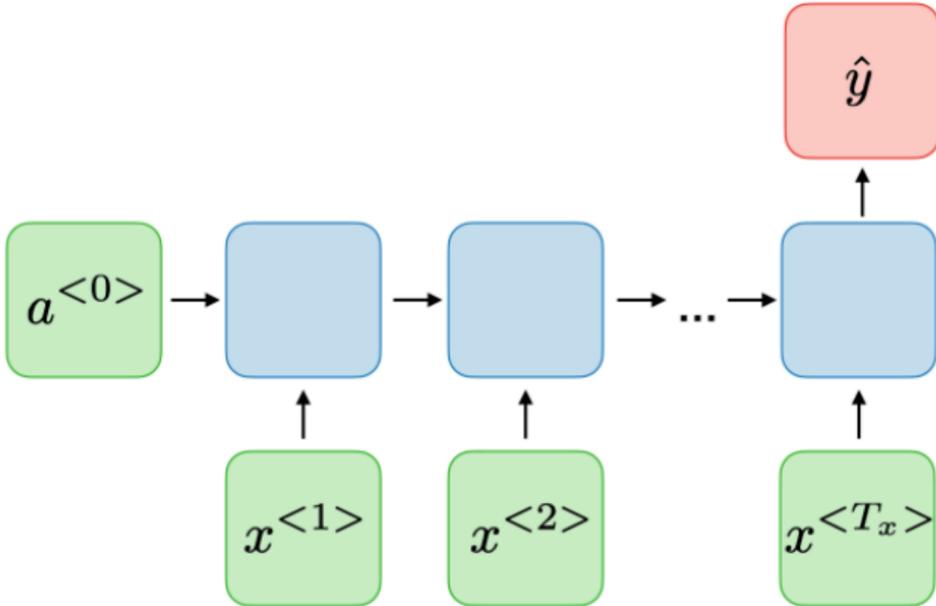
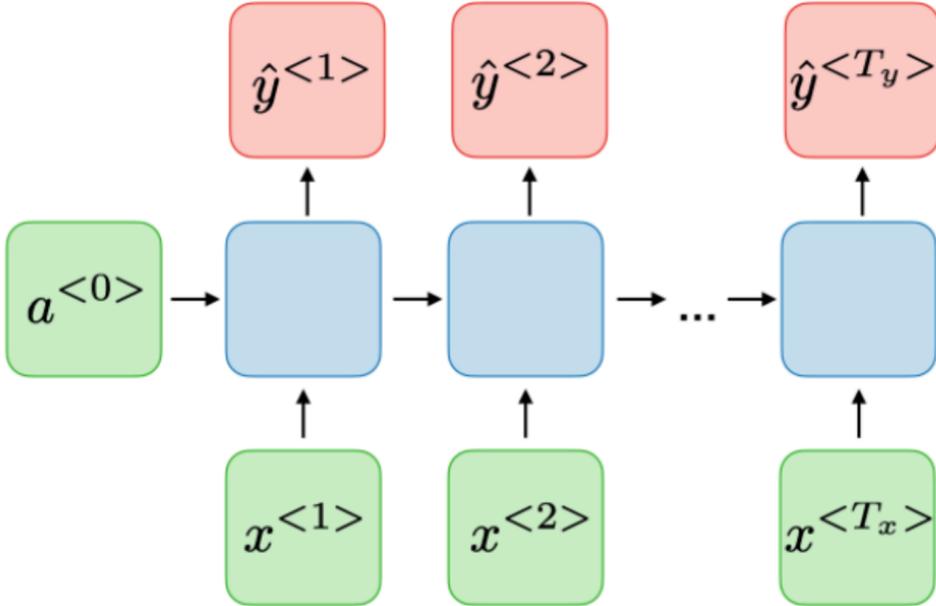
$g_1, g_2$  activation functions.

# Elman Networks (Simple Recurrent Networks)

□ **Commonly used activation functions** — The most common activation functions used in RNN modules are described below:

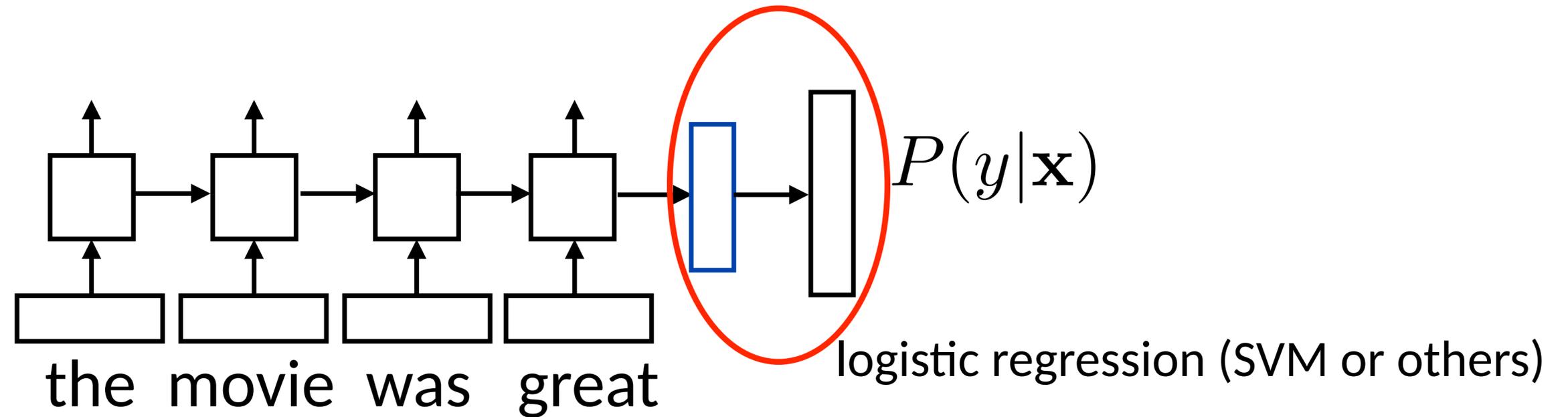
Sigmoid	Tanh	RELU
$g(z) = \frac{1}{1 + e^{-z}}$	$g(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$	$g(z) = \max(0, z)$
		

# Applications

Type	Illustration	Example
Many-to-one $T_x > 1, T_y = 1$	 <p>The diagram illustrates a many-to-one RNN architecture. It consists of a sequence of input nodes <math>x^{&lt;1&gt;}, x^{&lt;2&gt;}, \dots, x^{&lt;T_x&gt;}</math> (green boxes) feeding into a sequence of hidden state nodes (blue boxes). The first hidden state node also receives an initial state <math>a^{&lt;0&gt;}</math> (green box). The final hidden state node produces a single output node <math>\hat{y}</math> (red box).</p>	Sentiment classification
Many-to-many $T_x = T_y$	 <p>The diagram illustrates a many-to-many RNN architecture. It consists of a sequence of input nodes <math>x^{&lt;1&gt;}, x^{&lt;2&gt;}, \dots, x^{&lt;T_x&gt;}</math> (green boxes) feeding into a sequence of hidden state nodes (blue boxes). The first hidden state node also receives an initial state <math>a^{&lt;0&gt;}</math> (green box). Each hidden state node produces a corresponding output node <math>\hat{y}^{&lt;1&gt;}, \hat{y}^{&lt;2&gt;}, \dots, \hat{y}^{&lt;T_y&gt;}</math> (red boxes).</p>	Name entity recognition

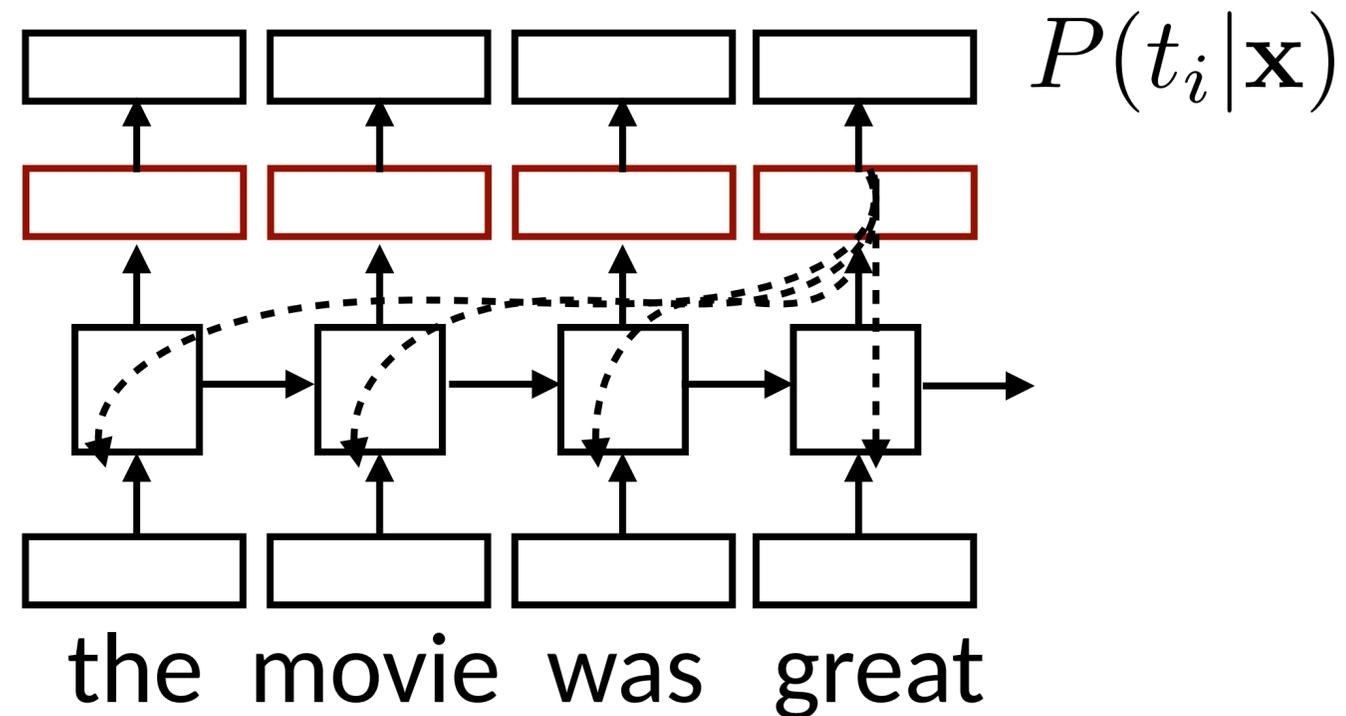
# Training RNNs

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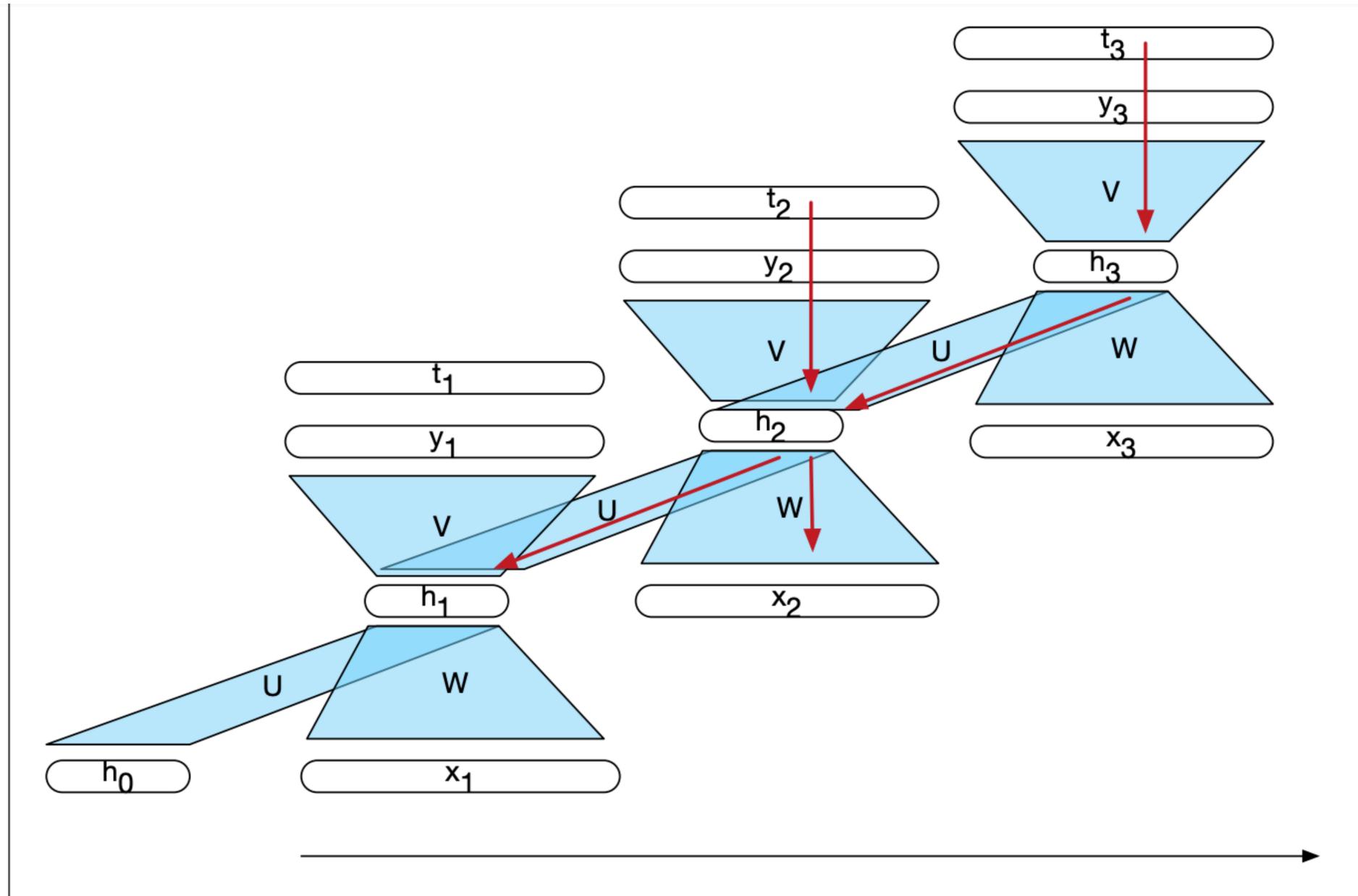
- ▶ Loss = negative log likelihood of probability of gold label, if using logistic regression
- ▶ Backpropagate through entire network
- ▶ Example: sentiment analysis

# Training RNNs



- ▶ Loss = negative log likelihood of probability of gold predictions, summed over the tags (i.e., all time steps)
- ▶ Loss terms backpropagate through network
- ▶ Example: language modeling (predict next word given context) or POS tagging

# Training Simple Recurrent Networks



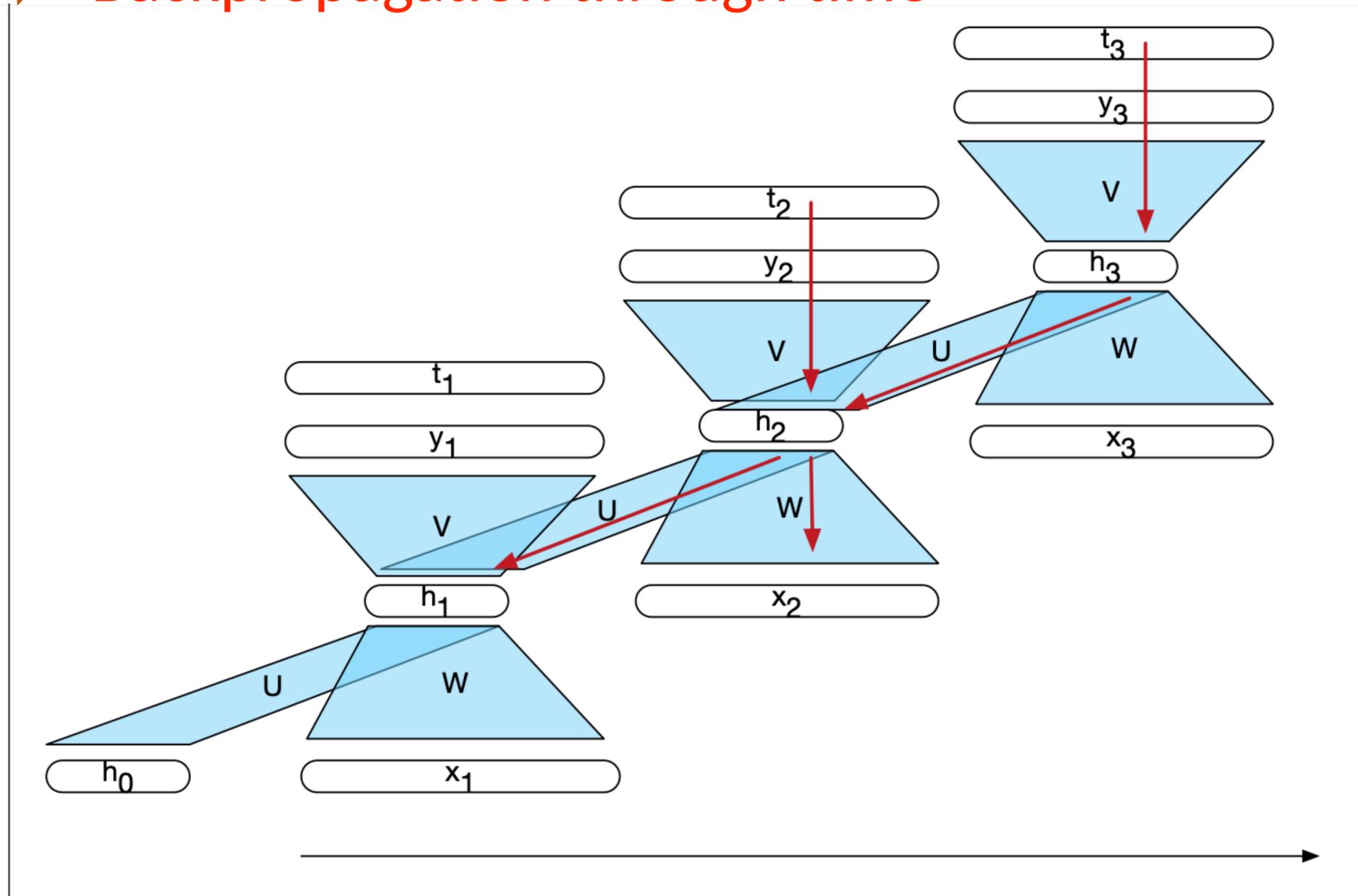
**Figure 9.6** The backpropagation of errors in a simple RNN  $t_i$  vectors represent the targets for each element of the sequence from the training data. The red arrows illustrate the flow of backpropagated errors required to calculate the gradients for  $U$ ,  $V$  and  $W$  at time 2. The two incoming arrows converging on  $h_2$  signal that these errors need to be summed.

Textbook JM, Chapter 9  
<https://web.stanford.edu/~jurafsky/slp3/9.pdf>

$t_i$  is the target and  $y_i$   
is predicted at each step  $i$

# Training Simple Recurrent Networks

## ► “Backpropagation through time”

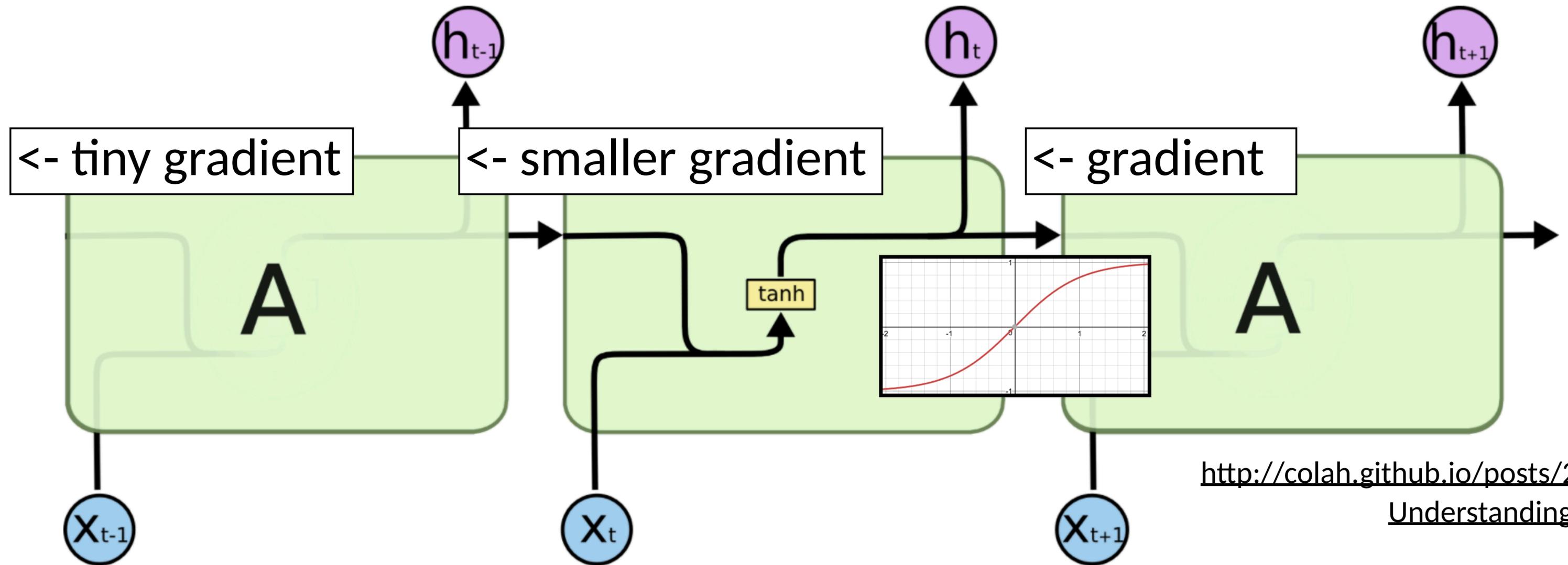


**Figure 9.6** The backpropagation of errors in a simple RNN  $t_i$  vectors represent the targets for each element of the sequence from the training data. The red arrows illustrate the flow of backpropagated errors required to calculate the gradients for  $U$ ,  $V$  and  $W$  at time 2. The two incoming arrows converging on  $h_2$  signal that these errors need to be summed.

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# Vanishing Gradient



<http://colah.github.io/posts/2015-08-Understanding-LSTMs/>

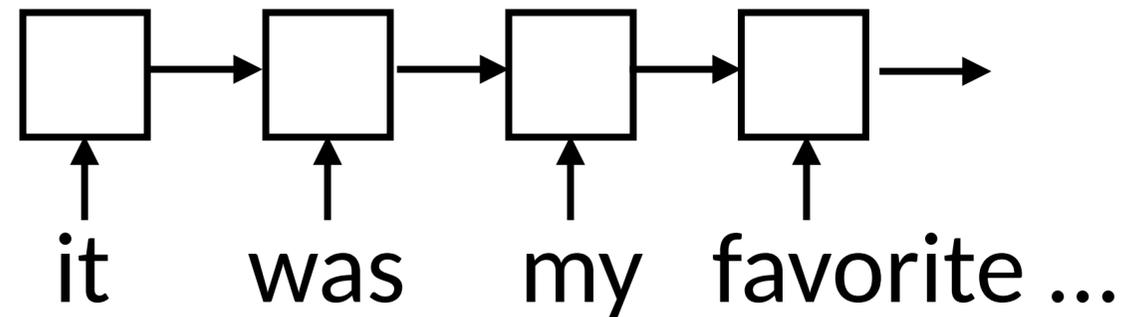
- ▶ Gradient diminishes during backpropagation
- ▶ Repeated multiplication by  $V$  causes problems in  $h_t = \tanh(Wx_t + Vh_{t-1} + b_h)$   
<https://stanford.edu/~shervine/teaching/cs-230/cheatsheet-recurrent-neural-networks#architecture>

# Training Elman Networks

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“it was my **favorite** movie of 2016, though it wasn't without **problems**” -> +

- ▶ RNN potentially needs to learn how to “remember” information for a long time!

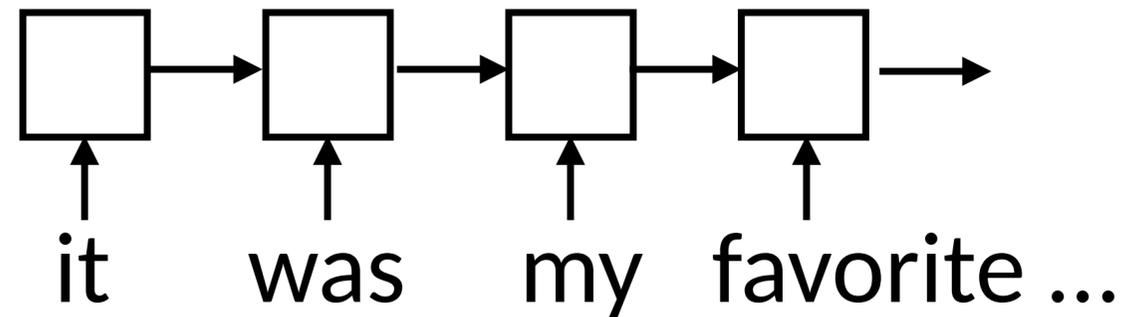


# Training Elman Networks

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“it was my **favorite** movie of 2016, though it wasn’t without **problems**” -> +

- ▶ RNN potentially needs to learn how to “remember” information for a long time!



Challenging to handle such “long-term dependencies”

# LSTMs/GRUs

- ▶ Designed to fix “vanishing gradient” problem using *gates*

# LSTMs/GRUs

□ **GRU/LSTM** — Gated Recurrent Unit (GRU) and Long Short-Term Memory units (LSTM) deal with the vanishing gradient problem encountered by traditional RNNs, with LSTM being a generalization of GRU. Below is a table summing up the characterizing equations of each architecture:

Characterization	Gated Recurrent Unit (GRU)	Long Short-Term Memory (LSTM)
$\tilde{c}^{<t>}$	$\tanh(W_c[\Gamma_r \star a^{<t-1>}, x^{<t>}] + b_c)$	$\tanh(W_c[\Gamma_r \star a^{<t-1>}, x^{<t>}] + b_c)$
$c^{<t>}$	$\Gamma_u \star \tilde{c}^{<t>} + (1 - \Gamma_u) \star c^{<t-1>}$	$\Gamma_u \star \tilde{c}^{<t>} + \Gamma_f \star c^{<t-1>}$
$a^{<t>}$	$c^{<t>}$	$\Gamma_o \star c^{<t>}$
Dependencies		

**Gates**

Remark: the sign  $\star$  denotes the element-wise multiplication between two vectors.

# LSTMs/GRUs

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□ **Types of gates** — In order to remedy the vanishing gradient problem, specific gates are used in some types of RNNs and usually have a well-defined purpose. They are usually noted  $\Gamma$  and are equal to:

$$\Gamma = \sigma(Wx^{<t>} + Ua^{<t-1>} + b)$$

where  $W, U, b$  are coefficients specific to the gate and  $\sigma$  is the sigmoid function. The main ones are summed up in the table below:

Type of gate	Role	Used in
Update gate $\Gamma_u$	How much past should matter now?	GRU, LSTM
Relevance gate $\Gamma_r$	Drop previous information?	GRU, LSTM
Forget gate $\Gamma_f$	Erase a cell or not?	LSTM
Output gate $\Gamma_o$	How much to reveal of a cell?	LSTM

# RNNs VS. LSTMs/GRUs

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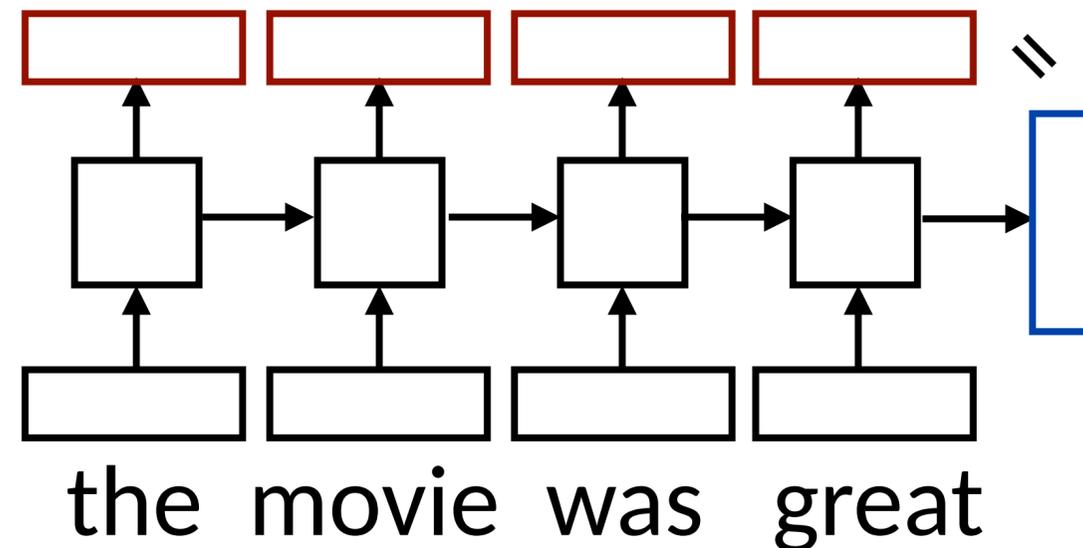
1. Why do RNNs suffer from vanishing and exploding gradients?
2. How do LSTMs keep the gradients from vanishing or explode?

See more:

<https://medium.com/datadriveninvestor/how-do-lstm-networks-solve-the-problem-of-vanishing-gradients-a6784971a577>

# What do RNNs produce?

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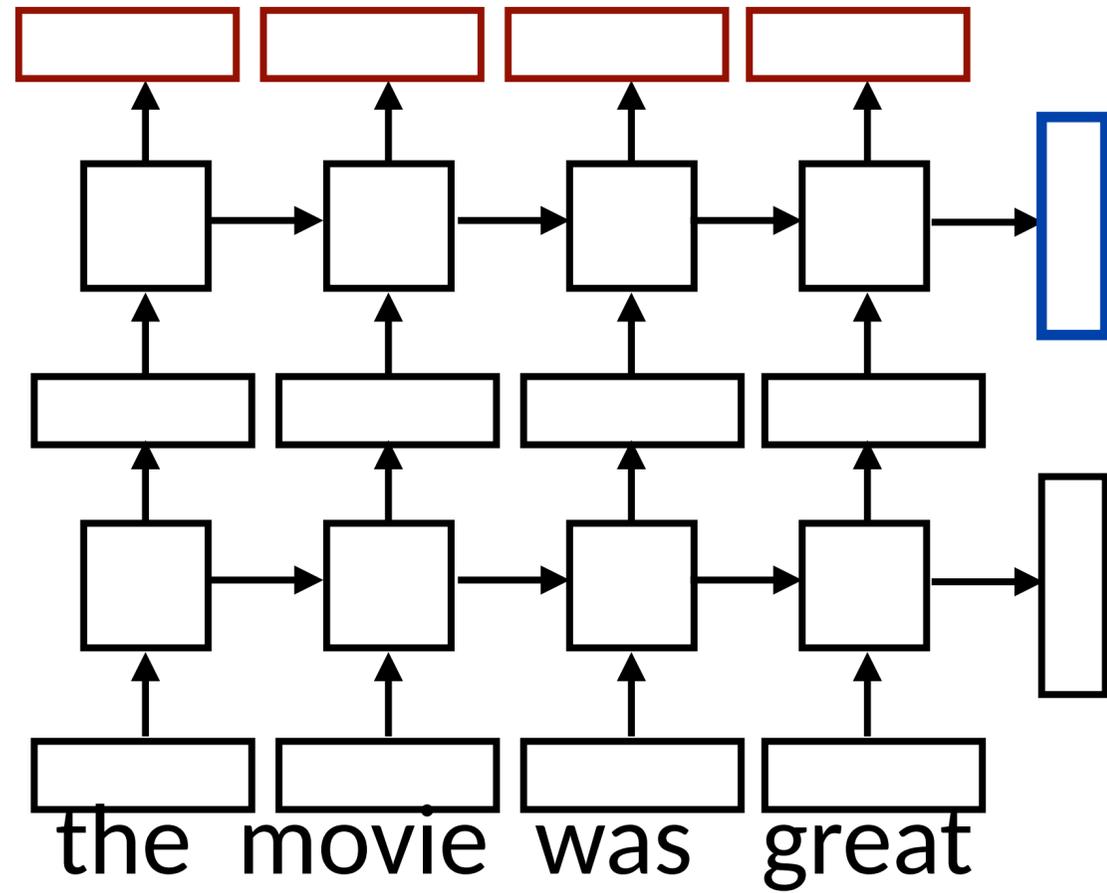


RNNs here include  
LSTMs /GRUs

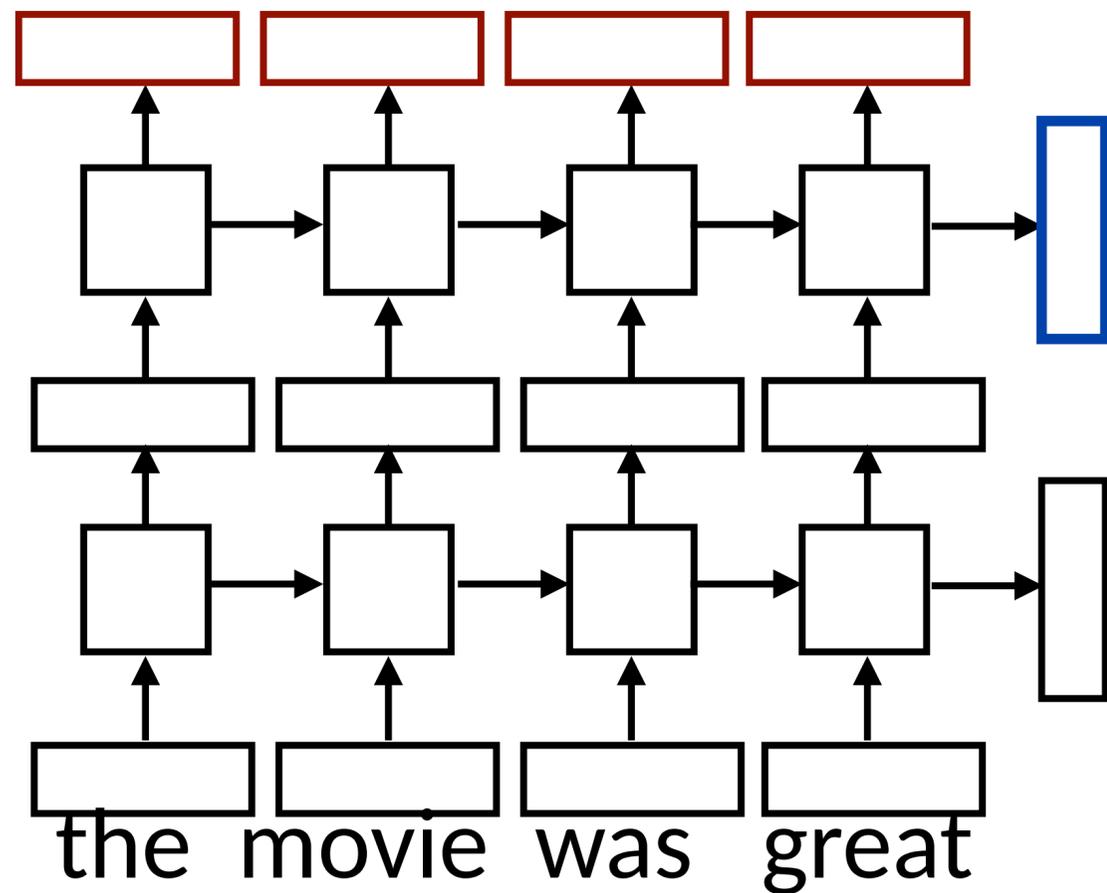
- ▶ **Encoding of the sentence** — can pass this to a decoder or make a classification decision about the sentence
- ▶ **Encoding of each word** — can pass this to another layer to make a prediction (can also pool these to get a different sentence encoding)
- ▶ RNN can be viewed as a transformation of a sequence of vectors into a sequence of context-dependent vectors

# Multilayer

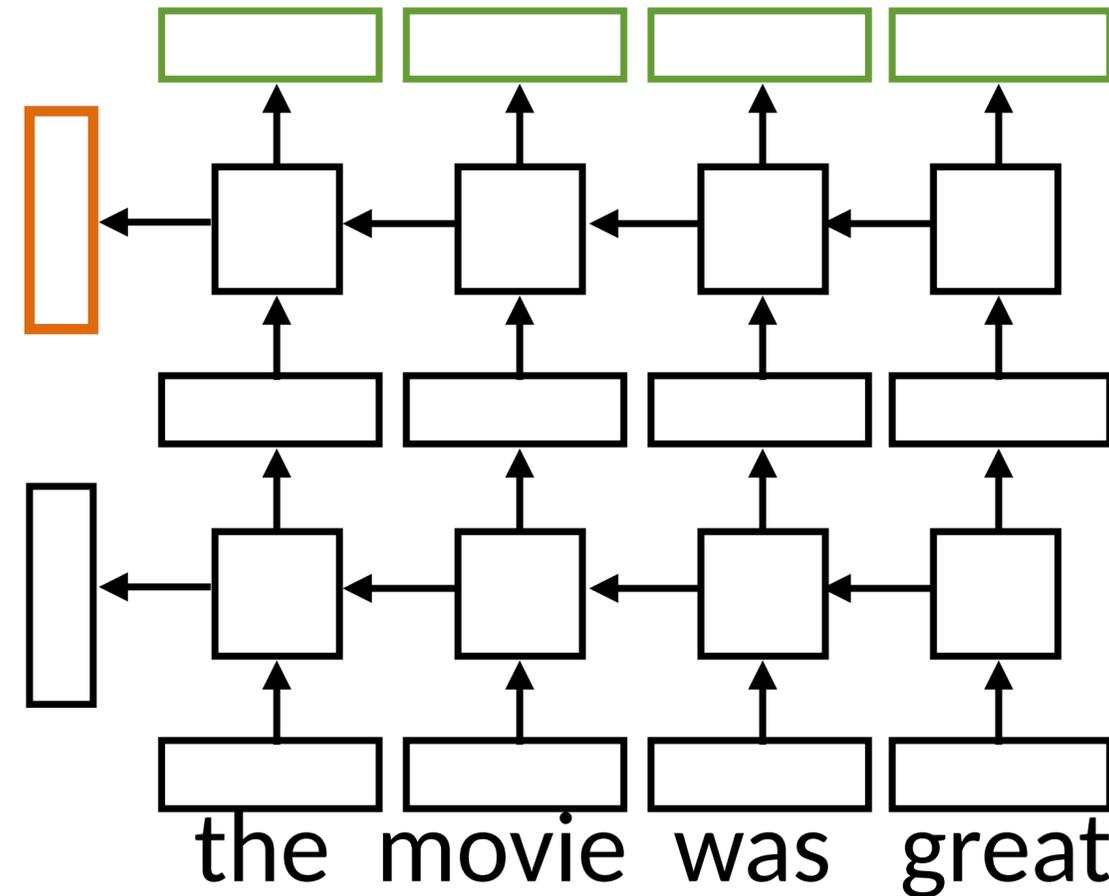
# RNN



# Multilayer Bidirectional RNN



- ▶ Sentence classification based on concatenation of both final outputs

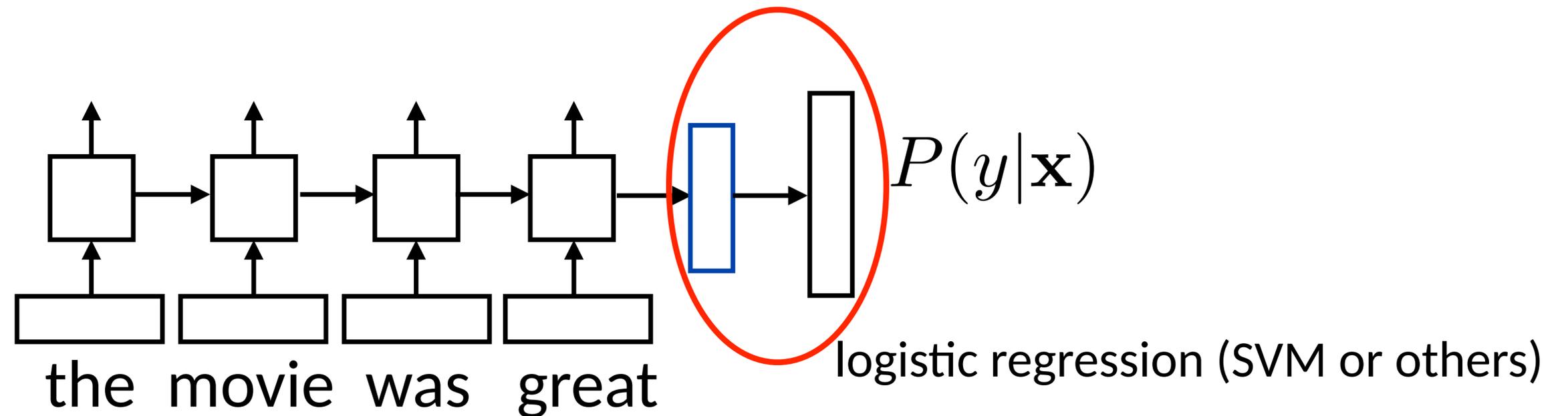


- ▶ Token classification based on concatenation of both directions' token representations



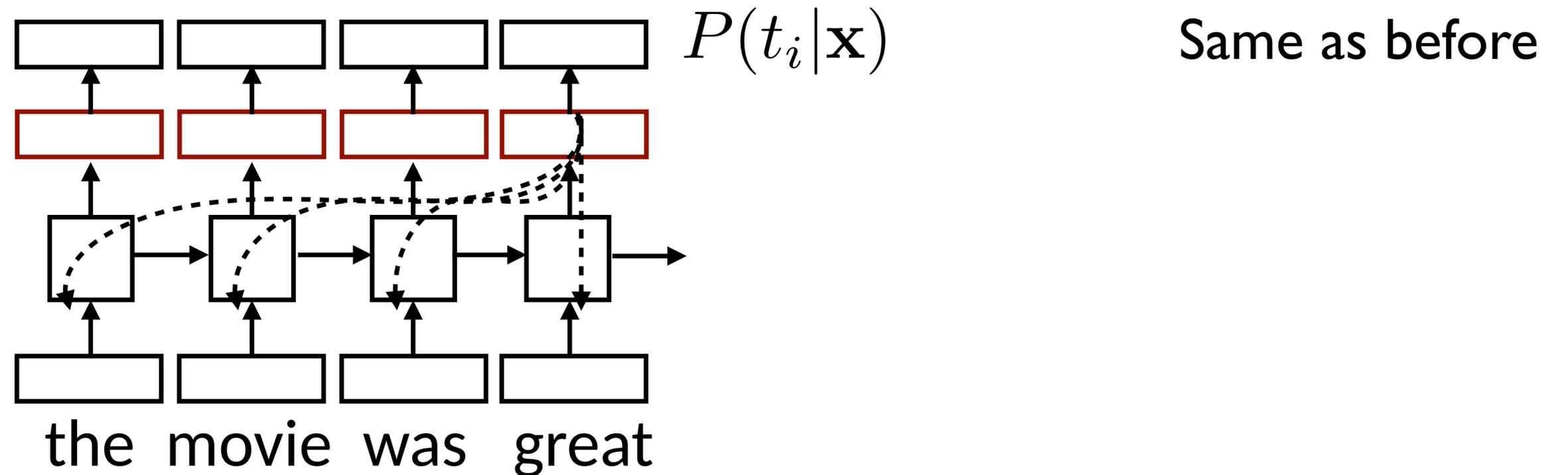
# Training RNNs in general

Same as before



- ▶ Loss = negative log likelihood of probability of gold label, if using logistic regression
- ▶ Backpropagate through entire network
- ▶ Example: sentiment analysis

# Training RNNs in general



- ▶ Loss = negative log likelihood of probability of gold predictions, summed over the tags
- ▶ Loss terms filter back through network
- ▶ Example: language modeling (predict next word given context) or POS tagging

# Applications

# What can LSTMs model?

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- ▶ Sentiment analysis (mentioned earlier)
  - ▶ Encode one sentence, predict
- ▶ Language models
  - ▶ Move left-to-right, per-token prediction (**later in the course**)
- ▶ Translation
  - ▶ Encode sentence + then decode, use token predictions for attention weights (**later in the course**)
- ▶ Textual entailment
  - ▶ Encode two sentences, predict

# Natural Language Inference

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Premise

Hypothesis

A boy plays in the snow

entails

A boy is outside

A man inspects the uniform of a figure

contradicts

The man is sleeping

An older and younger man smiling

neutral

Two men are smiling and laughing at cats playing

- ▶ Long history of this task: “Recognizing Textual Entailment” challenge in 2006 (Dagan, Glickman, Magnini)
- ▶ Early datasets: small (hundreds of pairs), very ambitious (lots of world knowledge, temporal reasoning, etc.)

# SNLI Dataset

- ▶ Show people captions for (unseen) images and solicit entailed / neural / contradictory statements
- ▶ >500,000 sentence pairs

- ▶ Encode each sentence and process

100D LSTM: 78% accuracy

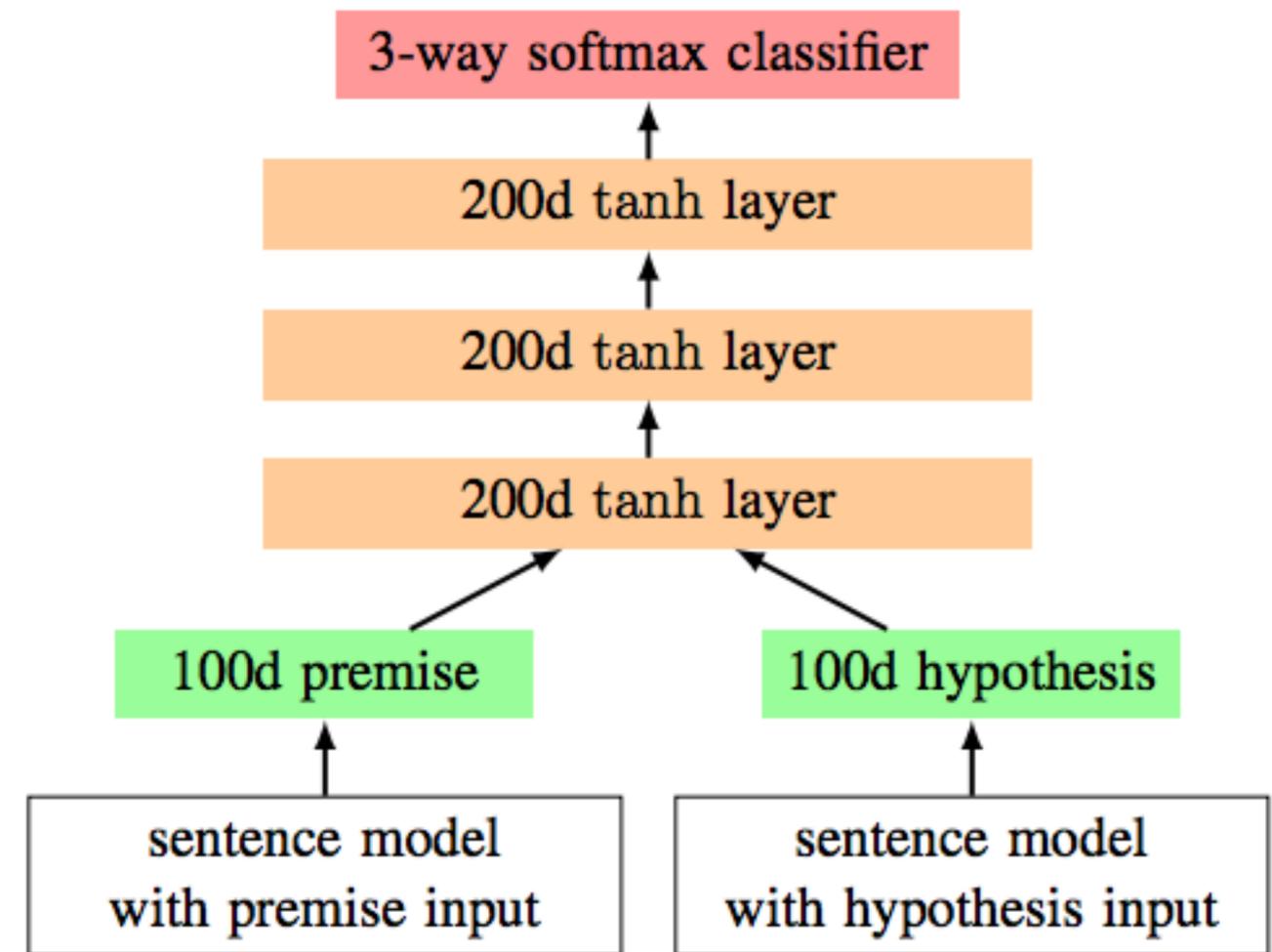
300D LSTM: 80% accuracy

(Bowman et al., 2016)

300D BiLSTM: 83% accuracy

(Liu et al., 2016)

- ▶ Later: better models for this



Bowman et al. (2015)

# Takeaways

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- ▶ RNNs can transduce inputs (produce one output for each input) or compress the whole input into a vector
- ▶ Useful for a range of tasks with sequential input: sentiment analysis, language modeling, natural language inference, machine translation, etc.