

## Lecture 3 - Initial and Boundary Value Problems

- Well Posed Problems

Physical problems have in general three characteristics which should be reflected in the mathematical equations we use to model them:

1. Existence - The phenomenon exists  $\Rightarrow$  there exists a solution to the differential equation
2. Uniqueness - Physical processes are causal: given the state at some time we should be able to produce only one state at all later times
3. Stability - Small changes in the initial conditions should lead to small changes in the output.

- Examples of well posed problems:

1.

$$\begin{aligned}\Delta u &= 0 \\ u|_{\partial\Omega} &= f(x)\end{aligned}$$

2.

$$\begin{aligned}\frac{\partial u}{\partial t} &= \Delta u \\ u(x, 0) &= g(x)\end{aligned}$$

The heat equation smooths things out.

By contrast, the backwards heat equation,

$$\begin{aligned}\frac{\partial u}{\partial t} &= -\Delta u \\ u(x, 0) &= f(x)\end{aligned}$$

is ill posed.

- 

$$\begin{aligned}u &= \sum_n a_n(t) \sin(nx) \\ \Delta u &= \sum_n -n^2 a_n(t) \sin(nx) \\ \frac{\partial u}{\partial t} &= \sum_n \dot{a}_n(t) \sin(nx) \text{ so} \\ \dot{a}_n(t) &= -n^2 a_n(t) \Rightarrow \frac{\partial u}{\partial t} = \Delta u \\ a_n(t) &= e^{-n^2 t} a_n(0)\end{aligned}$$

so for the heat equation high frequencies decay much faster than low frequencies.

For the backward heat equation

$$\frac{\partial u}{\partial t} = -\Delta u,$$

we instead have

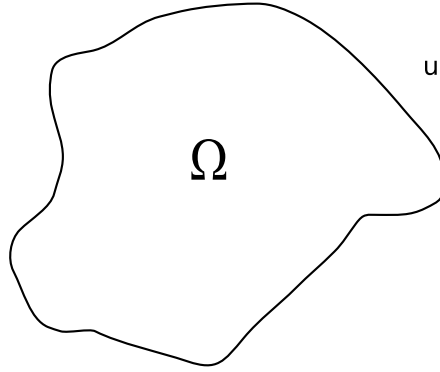
$$a_n(t) = e^{n^2 t} a_n(0).$$

Here, higher frequencies blow up.

- Initial and Boundary Conditions

Initial conditions:

- $u(x, t_0) = \phi(x)$
- $u(x, t_0) = \phi(x), \frac{\partial u}{\partial x}(x, t_0) = \psi(x)$



Dirichlet conditions if  $u|_{\partial\Omega}$  is specified

Neumann conditions if  $\frac{\partial u}{\partial n}|_{\partial\Omega}$  is specified

Robin conditions if  $a\frac{\partial u}{\partial n} + bu|_{\partial\Omega}$  is specified

- Solutions as minimizers:

$$E(u) = \int_{\Omega} |\nabla u|^2 = \int_{\Omega} \left( \left| \frac{\partial u}{\partial x^1} \right|^2 + \left| \frac{\partial u}{\partial x^2} \right|^2 + \left| \frac{\partial u}{\partial x^3} \right|^2 \right)$$

Minimize energy:

$$\begin{aligned} 0 &= \frac{dE}{d\epsilon}(u + \epsilon v)|_{\epsilon=0} = \int_{\Omega} \langle \nabla u, \nabla v \rangle \\ &= \int_{\Omega} \left( \sum_{i=1}^3 \frac{\partial u}{\partial x^i} \frac{\partial v}{\partial x^i} \right) \\ &= \int_{\Omega} - \left( \sum_{i=1}^3 \frac{\partial^2 u}{\partial x^{i2}} \cdot v \right) \\ \sum_{i=1}^3 \frac{\partial^2 u}{\partial x^{i2}} &= 0 \Leftrightarrow \Delta u = 0 \end{aligned}$$

Suppose  $u$  is free in  $\partial\Omega$ . Then the divergence theorem gives that

$$\int \nabla \cdot (v \nabla u) = \int \langle \nabla u, \nabla v \rangle + \int v \Delta u$$

hence 
$$\int \langle \nabla u, \nabla v \rangle = \int_{\partial\Omega} v \frac{\partial u}{\partial n} - \int (\Delta u) v$$

where the Neumann condition is now used.

- Conditions at infinity

1. Schrödinger equation -  $\int_{\mathbb{R}^3} |u|^2 = 1$
2. Laplace equation -  $\int |\nabla u|^2 = 1$
3. Wave equation

$$\frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2} + Vu$$

$\sin(\omega(t \pm x))$  are solutions to the  $V \equiv 0$  case.