

Numerical Integration

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Quadrature

- We talk in terms of Quadrature Rules
 - **1.** The process of making something square. **2.** *Mathematics* The process of constructing a square equal in area to a given surface. **3.** *Astronomy* A configuration in which the position of one celestial body is 90° from another celestial body, as measured from a third.
 - The American Heritage® Dictionary: Fourth Edition. 2000



Outline

- Definite Integrals
- Lower and Upper Sums
 - Riemann Integration or Riemann Sums
- Uniformly-spaced samples
 - Trapezoid Rules
 - Romberg Integration
 - Simpson's Rules
 - Adaptive Simpson's Scheme
- Non-uniformly spaced samples
 - Gaussian Quadrature Formulas

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Motivation

What does an integral represent?

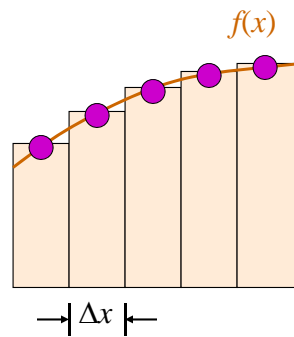
$$\int_a^b f(x)dx = \text{area} \quad \int_c^d \int_a^b f(x)dx dy = \text{volume}$$

Basic definition of an integral:

$$\int_a^b f(x)dx = \lim_{n \rightarrow \infty} \sum_{k=1}^n f(x_k) \Delta x$$

where $\Delta x = \frac{b-a}{n}$

sum of height \times width



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Motivation

- Evaluate the integral, $I = \int_a^b f(x)dx$ without doing the calculation analytically.
- Necessary when either:
 - Integrand is too complicated to integrate analytically

$$\int_0^2 \frac{2 + \cos(1 + \sqrt{x})}{\sqrt{1 + 0.5x}} e^{0.5x} dx$$

- Integrand is not precisely defined by an equation, i.e., we are given a set of data (x_i, y_i) , $i = 1, 2, 3, \dots, n$

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Reimann Integral Theorem

- Integration is a summing process. Thus virtually all numerical approximations can be represented by

$$I = \int_a^b f(x)dx = \sum_{i=1}^n w_i f(x_i) + E_t$$

in which w_i are the weights, x_i are the sampling points, and E_t is the truncation error

- Valid for any function that is continuous on the closed and bounded interval of integration.

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Partitioning the Integral

- The most common numerical integration formula is based on **equally spaced data points**.

$$\int_{x_0}^{x_n} f(x) dx$$

- Divide $[x_0, x_n]$ into n *intervals* ($n \geq 1$)

$$\int_{x_0}^{x_n} f(x) dx = \int_{x_0}^{x_1} f(x) dx + \int_{x_1}^{x_2} f(x) dx + \cdots + \int_{x_{n-1}}^{x_n} f(x) dx$$

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Upper Sums

- Assume that $f(x) > 0$ everywhere.
- If within each interval, we could determine the maximum value of the function, then we have:

$$\int_{x_0}^{x_n} f(x) dx \leq \sum_{i=0}^{n-1} M_i (x_{i+1} - x_i)$$

- where

$$M_i = \sup \{ f(x) : x_i \leq x \leq x_{i+1} \}$$

Supremum - least upper bound

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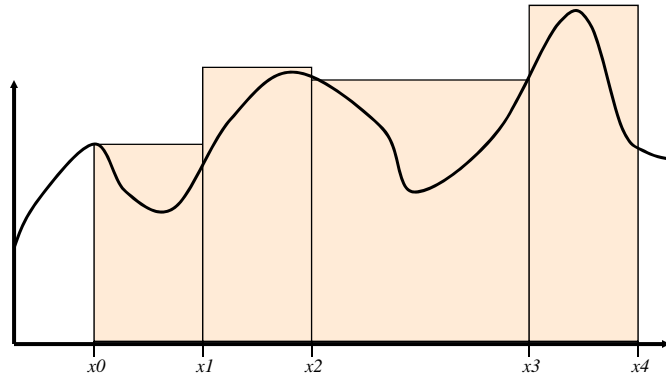
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Upper Sums

- Graphically:



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Lower Sums

- Likewise, still assuming that $f(x) > 0$ everywhere.
- If within each interval, we could determine the minimum value of the function, then we have:

$$\int_{x_0}^{x_n} f(x) \geq \sum_{i=0}^{n-1} m_i (x_{i+1} - x_i)$$

- where

$$m_i = \inf \{ f(x) : x_i \leq x \leq x_{i+1} \}$$

Infimum - greatest lower bound

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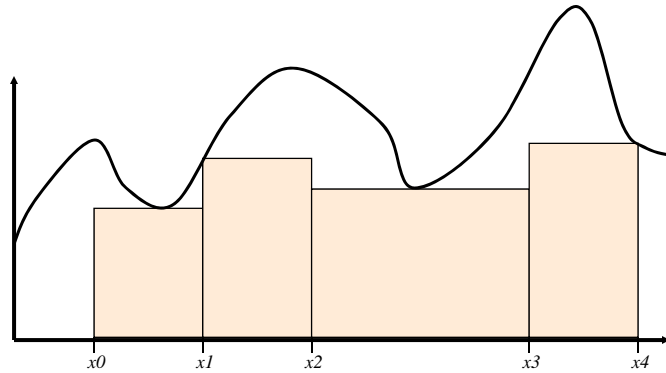
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Lower Sums

- Graphically



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Finer Partitions

- We now have a bound on the integral of the function for some partition (x_0, \dots, x_n) :

$$\sum_{i=0}^{n-1} m_i (x_{i+1} - x_i) \leq \int_{x_0}^{x_n} f(x) \leq \sum_{i=0}^{n-1} M_i (x_{i+1} - x_i)$$

- As $n \rightarrow \infty$, one would assume that the sum of the upper bounds and the sum of the lower bounds approach each other.
- This is the case for most functions, and we call these Riemann-integrable functions.

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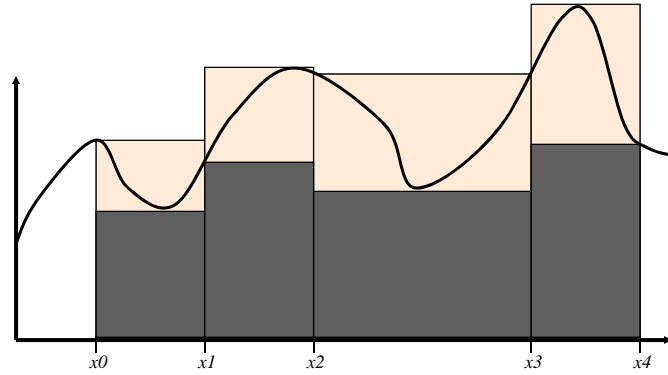
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Bounding the Integral

- Graphically



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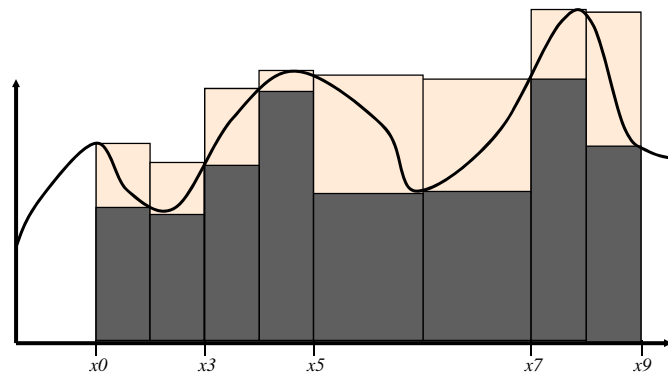
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Bounding the Integral

- Halving each interval (*much like Lab1*):



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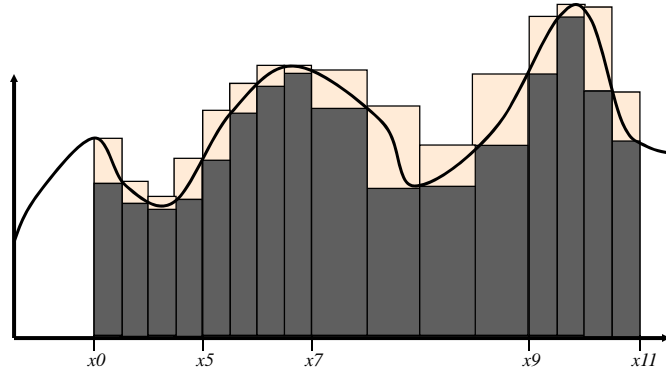
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Bounding the Integral

- One more time:



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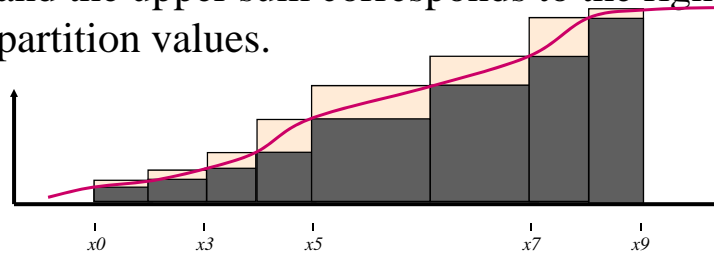
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Monotonic Functions

- Note that if a function is monotonically increasing (or decreasing), then the lower sum corresponds to the left partition values, and the upper sum corresponds to the right partition values.



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Lab1 and Integration

- Thinking back to lab1, what were the limits or the integration?
- Is the sin function monotonic on this interval?
- Should the Reiman sum be an upper or lower sum?

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Polynomial Approximation

- Rather than search for the maximum or minimum, we replace $f(x)$ with a known and simple function.
- Within each interval we approximate $f(x)$ by an m^{th} order polynomial.

$$p_m(x) = a_0 + a_1x + a_2x^2 + \dots + a_mx^m$$

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Newton-Cotes Formulas

- The m 's (order of the polynomials) may be the same or different.

$$\int_{x_0}^{x_n} f(x)dx = \int_{x_0}^{x_0+m_1} p_{m_1}(x)dx + \int_{x_0+m_1}^{x_0+m_1+m_2} p_{m_2}(x)dx + \dots + \int_{x_{n-m_n}}^{x_n} p_{m_n}(x)dx$$

- Different choices for m 's lead to different formulas:

m	Polynomial	Formula	Error
1	linear	Trapezoid	$O(h^2)$
2	quadratic	Simpson's 1/3	$O(h^4)$
3	cubic	Simpson's 3/8	$O(h^4)$

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Trapezoid Rule

- Simplest way to approximate the area under a curve – using **first order polynomial** (a straight line)
- Using Newton's form of the interpolating polynomial:

$$p_1(x) = f(a) + \frac{f(b) - f(a)}{b - a}(x - a)$$

- Now, solve for the integral:

$$I = \int_a^b f(x)dx \approx \int_a^b p_1(x)dx$$

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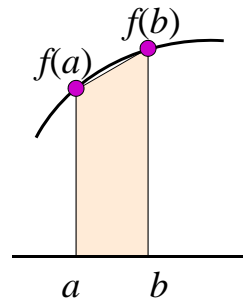


Trapezoid Rule

$$I \approx \int_a^b \left[f(a) + \frac{f(b) - f(a)}{b - a} (x - a) \right] dx$$

Trapezoid Rule

$$I \approx \frac{(b - a)}{2} [f(a) + f(b)]$$



$I \approx \text{width} \times \text{average height}$

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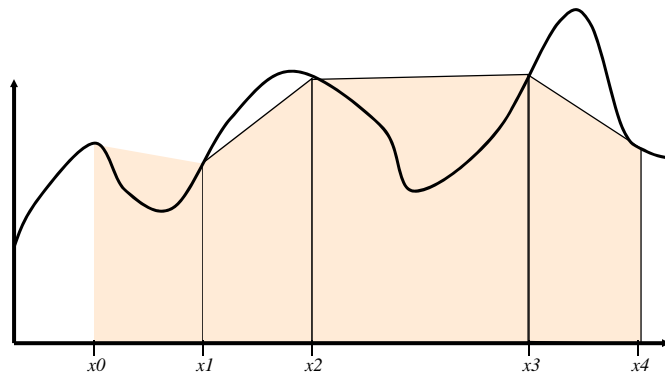
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Trapezoid Rule

- Improvement?



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Trapezoid Rule Error

- The integration error is:

$$E_t = -\frac{1}{12} f''(\xi) h^3 = -\frac{(b-a)}{12} f''(\xi) h^2 \quad O(h^3)$$

- Where $h = b - a$ and ξ is an unknown point where $a < \xi < b$ (intermediate value theorem)
- You get exact integration if the function, f , is linear ($f'' = 0$)

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Example

Integrate from $f(x) = e^{-x^2}$ $a = 0$ to $b = 2$

Use trapezoidal rule:

$$\begin{aligned} I &= \int_0^2 e^{-x^2} dx \\ &\approx \frac{(b-a)}{2} [f(a) + f(b)] = \frac{(2-0)}{2} [f(2) + f(0)] \\ &= 1 \times (e^{-4} + e^0) = 1.0183 \end{aligned}$$

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Example

Estimate error: $E_t = -\frac{1}{12} f''(\xi) h^3$

Where $h = b - a$ and $a < \xi < b$

Don't know ξ - use average value

$$f''(x) = (-2 + 4x^2)e^{-x^2}$$

$$f''(0) = -2$$

$$h = 2 - 0 = 2$$

$$f''(2) = 0.2564$$

$$E_t \approx E_a = -\frac{2^3 [f''(0) + f''(2)]}{12 \cdot 2} = 0.58$$

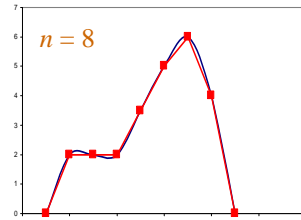
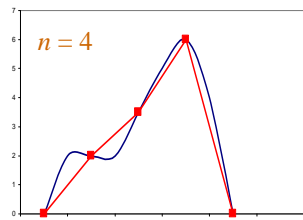
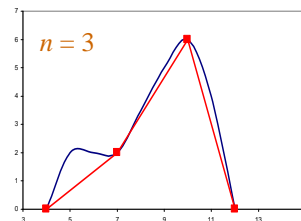
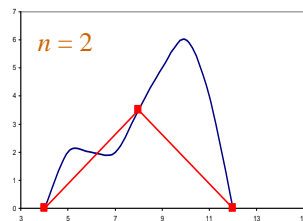
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More intervals, better result [error $\sim O(h^2)$]



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Composite Trapezoid Rule

- If we do multiple intervals, we can avoid duplicate function evaluations and operations:
- Use $n+1$ equally spaced points.
- Each interval has: $h = \frac{b-a}{n}$
- Break up the limits of integration and expand.

$$I = \int_a^{a+h} f(x)dx + \int_{a+h}^{a+2h} f(x)dx + \dots + \int_{b-h}^b f(x)dx$$

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Composite Trapezoid Rule

- Substituting the trapezoid rule for each integral.

$$\begin{aligned}
 I &= \int_a^{a+h} f(x)dx + \int_{a+h}^{a+2h} f(x)dx + \dots + \int_{b-h}^b f(x)dx \\
 &= \frac{(a+h-a)}{2} [f(a) + f(a+h)] + \frac{(a+2h-a-h)}{2} [f(a+h) + f(a+2h)] \\
 &\quad + \dots + \frac{(b-b+h)}{2} [f(b-h) + f(b)]
 \end{aligned}$$

- Results in the Composite Trapezoid Formula:

$$I = \frac{h}{2} \left[f(a) + 2 \sum_{i=1}^{n-1} f(a+ih) + f(b) \right]$$

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Composite Trapezoid Rule

- Think of this as the *width* times the average *height*.

$$I = \frac{h}{2} \left[f(a) + 2 \sum_{i=1}^{n-1} f(a+ih) + f(b) \right]$$
$$= \underbrace{(b-a)}_{\text{width}} \underbrace{\frac{f(a) + 2 \sum_{i=1}^{n-1} f(a+ih) + f(b)}{2n}}_{\text{Average height}}$$

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Error

- The error can be estimated as:

$$E_a = \frac{(b-a)h^2}{12} \bar{f}'' = \frac{(b-a)^3}{12n^2} \bar{f}'' \quad O(h^2)$$

- Where, \bar{f}'' is the average second derivative.
- If n is doubled, $h \rightarrow h/2$ and $E_a \rightarrow E_a/4$
- Note, that the error is dependent upon the *width* of the area being integrated.

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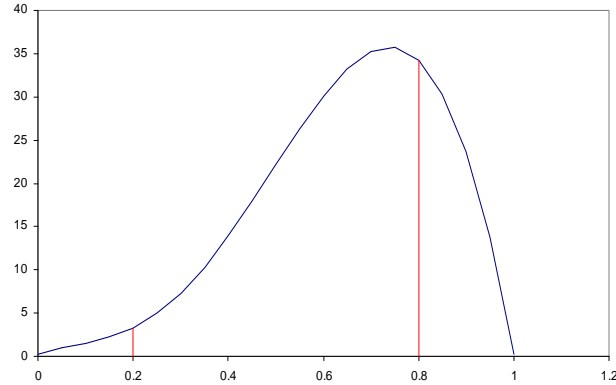
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Example

- Integrate: $f(x) = 0.3 + 20x - 140x^2 + 730x^3 - 810x^4 + 200x^5$
- from $a=0.2$
to $b=0.8$



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Example

- A single application of the Trapezoid rule.

$$\begin{aligned} I &= (b-a) \frac{f(a) + f(b)}{2} \\ &= (0.8 - 0.2) \frac{34.22 + 3.81}{2} \\ &= 11.26 \end{aligned}$$

- Error: $E_T = -\frac{1}{12} f''(\xi)(b-a)^3$

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Example

- We don't know ξ so approximate with average f''

$$f'(x) = 20 - 280x + 2190x^2 - 3240x^3 + 1000x^4$$

$$f''(x) = -280 + 4380x - 9720x^2 + 4000x^3$$

$$\begin{aligned}\bar{f}''(x) &= \frac{\int_{0.2}^{0.8} f'' dx}{0.8 - 0.2} \\ &= \frac{f'(0.8) - f'(0.2)}{0.8 - 0.2} = -131.6\end{aligned}$$

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Example

- The error can thus be estimated as:

$$\begin{aligned}E_i &= \frac{(b-a)h^2}{12} \bar{f}'' = \frac{(b-a)^3}{12n^2} \bar{f}'' \\ &= -\frac{1}{12}(-131.6)(0.8-0.2)^3 = 2.37\end{aligned}$$

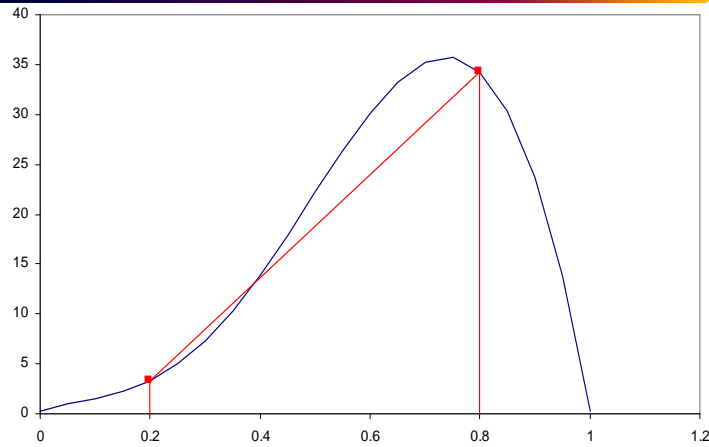
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True value of integral is 12.82. Trapezoid rule is 11.26 - within approx error - E_t is 12%



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Using Three Intervals

- Use intervals (0.2,0.4),(0.4,0.6),(0.6,0.8):
 - ($n = 3, h = 0.2$)

$$\begin{aligned} I &= (b-a) \frac{f(a) + 2 \sum_{i=1}^{n-1} f(a+ih) + f(b)}{2n} \\ &= (0.8-0.2) \frac{f(0.2) + 2[f(0.4) + f(0.6)] + f(0.8)}{(2)(3)} \\ &= 0.6 \frac{3.31 + 2(13.93 + 30.16) + 34.22}{6} \\ &= 12.57 \end{aligned}$$

True value of integral is 12.82

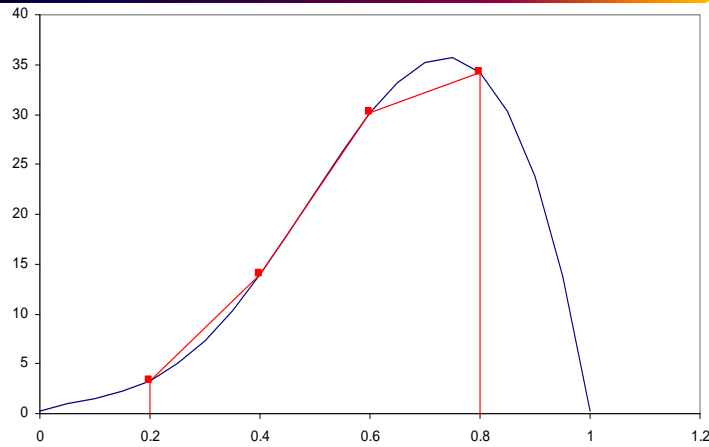
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E_t is now 2%



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Using Six Intervals

- Use intervals (0.2,0.3),(0.3,0.4), etc.
 - ($n = 6, h = 0.1$)

$$\begin{aligned} I &= (0.8 - 0.2) \frac{f(0.2) + 2[f(0.3) + f(0.4) + f(0.5) + f(0.6) + f(0.7)] + f(0.8)}{(2)(6)} \\ &= 0.6 \frac{3.31 + 2(7.34 + 13.93 + 22.18 + 30.16 + 35.22) + 34.22}{12} \\ &= 12.76 \end{aligned}$$

True value of integral is 12.82

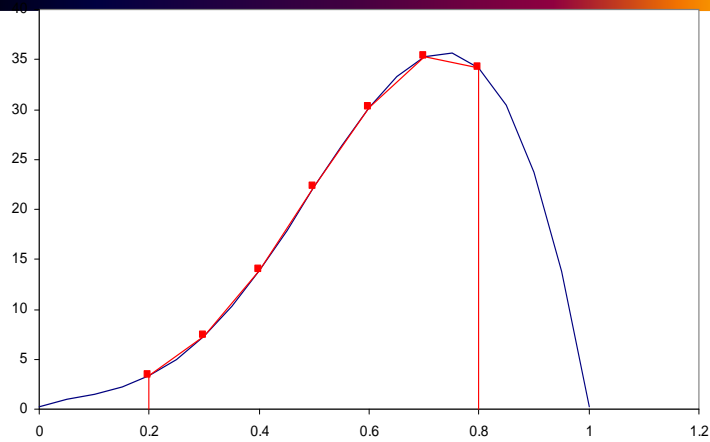
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E_t is now 0.5%



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Multi-dimensional Integration

- Consider a two-dimensional case.

$$\begin{aligned} \int_0^1 \int_0^1 f(x, y) dx dy &\approx \int_0^1 \sum_{i=0}^n A_i f\left(\frac{i}{n}, y\right) dy \\ &= \sum_{i=0}^n A_i \int_0^1 f\left(\frac{i}{n}, y\right) dy \\ &\approx \sum_{i=0}^n A_i \sum_{j=0}^n A_j f\left(\frac{i}{n}, \frac{j}{n}\right) \\ &= \sum_{i=0}^n \sum_{j=0}^n A_i A_j f\left(\frac{i}{n}, \frac{j}{n}\right) \end{aligned}$$

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Multi-dimensional Integration

- For the Trapezoid Rule, this leads to weights in the following pattern:

1	1	2	2	2	2	2	1
2	2	4	4	4	4	4	2
2	2	4	4	4	4	4	2
2	2	4	4	4	4	4	2
2	2	4	4	4	4	4	2
2	2	4	4	4	4	4	2
1	1	2	2	2	2	2	1

$$A_{ij} = \frac{1}{4n^2} \begin{cases} 1 & i \in \{0, n\} & j \in \{0, n\} \\ 2 & i \in [1, \dots, n-2] & j \in \{1, n-1\} \\ 2 & i \in \{1, n-1\} & j \in [1, \dots, n-1] \\ 4 & i \in [1, \dots, n-2] & j \in [1, \dots, n-2] \end{cases}$$

1	2	2	2	2	2	1
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Multi-dimensional Integration

- If we use the weights from the Trapezoid rule, the error is still $O(h^2)$.
- However, there are now n^2 function evaluations.
 - Equally-spaced samples on a square region.

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Multi-dimensional Integration

- In general, given k dimensions, we have $N = n^k$ function evaluations:

$$O(h^2) = O(n^{-2}) = O\left((n^k)^{\frac{2}{k}}\right) = O\left(N^{\frac{2}{k}}\right)$$

- If the dimension is high, this leads to a significant amount of additional work in going from $h \rightarrow h/2$.
 - Remember this for Monte-Carlo Integration.

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Reducing the Error

- To improve the estimate of the integral, we can either:
 - Add more intervals
 - Use a higher order polynomial
 - Use Richardson Extrapolation to examine the limit as $h \rightarrow 0$.
 - Called Romberg Integration

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Adding More Intervals

- If we have an estimate for one value of h , do we need to recompute everything for a value of $h/2$?

$$I_h = \frac{h}{2} \left[f(a) + 2 \sum_{i=1}^{n-1} f(a+ih) + f(b) \right]$$

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Adding More Intervals

- This is called the **Recursive Trapezoid Rule** in the book.
- We have $n \rightarrow 2n$ and $h \rightarrow h/2$.

$$\begin{aligned} I_{\frac{h}{2}} &= \frac{h}{4} \left[f(a) + 2 \sum_{i=1}^{2n-1} f\left(a + i \frac{h}{2}\right) + f(b) \right] \\ &= \frac{h}{4} \left[f(a) + 2 \sum_{i=1}^{n-1} f(a+ih) + 2 \sum_{i=0}^{n-1} f\left(a+ih + \frac{h}{2}\right) + f(b) \right] \\ &= \frac{I_h}{2} + \frac{h}{4} \left[2 \sum_{i=0}^{n-1} f\left(a+ih + \frac{h}{2}\right) \right] \end{aligned}$$

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Recall Richardson Extrapolation

- Given two numerical estimates obtained using different h 's, compute higher-order estimate
- Starting with a step size h_1 , the exact value is

$$A = A(h_1) + O(h_1^n)$$

- Suppose we reduce step size to h_2

$$A = A(h_2) + O(h_2^n)$$

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Richardson Extrapolation

- Multiplying the 2nd eqn by $(h_1/h_2)^n$ and subtracting from the 1st eqn:

$$A = \frac{\left(\frac{h_1}{h_2}\right)^n A(h_2) - A(h_1)}{\left(\frac{h_1}{h_2}\right)^n - 1}$$

- The new error term is generally $O(h_1^{n+1})$ or $O(h_1^{n+2})$.

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Richardson Extrapolation

- The true integral value can be written

$$I = I(h) + E(h)$$

- This is true for any iteration

$$I = I(h_1) + E(h_1) = I(h_2) + E(h_2)$$

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Richardson Extrapolation

- For example: Using ($n = 2$)

$$E \approx ch^2 \bar{f}'' \quad [\text{error} = O(h^2)]$$

- where c is a constant
- Therefore:

$$\frac{E(h_1)}{E(h_2)} \approx \frac{h_1^2}{h_2^2}$$

order of error in
trapezoidal rule

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Richardson Extrapolation

- This leads to:

$$E(h_1) \approx E(h_2) \frac{h_1^2}{h_2^2}$$

- For integration, we have:

$$I(h_1) + E(h_2) \frac{h_1^2}{h_2^2} \approx I(h_2) + E(h_2)$$

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Richardson Extrapolation

- Solving for $E(h_2)$:

$$E(h_2) \approx \frac{I(h_1) - I(h_2)}{1 - \frac{h_1^2}{h_2^2}}$$

- And plugging back into the estimated integral.

$$I = I(h_2) + E(h_2)$$

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Richardson Extrapolation

- Leads to:

$$I \approx I(h_2) + \frac{1}{(h_1/h_2)^2 - 1} [I(h_2) - I(h_1)]$$

- Letting $h_2 = h_1/2$

$$I \approx I(h_2) + \frac{1}{2^2 - 1} [I(h_2) - I(h_1)]$$

$$I \approx \frac{4}{3} I(h_2) - \frac{1}{3} I(h_1)$$

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Romberg Integration

- We combined two $O(h^2)$ estimates to get an $O(h^4)$ estimate.
- Can also combine two $O(h^4)$ estimates to get an $O(h^6)$ estimate.

$$I \approx \frac{16}{15} I(h_m) - \frac{1}{15} I(h_r)$$

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Romberg Integration

- Greater weight is placed on the more accurate estimate.
- Weighting coefficients sum to unity
 - i.e, $(16-1)/15=1$
- Can continue, by combining two $O(h^6)$ estimates to get an $O(h^8)$ estimate.

$$I \approx \frac{64}{63} I(h_m) - \frac{1}{63} I(h_l)$$

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Romberg Integration

- General pattern is called **Romberg Integration**

$$I_{j,k+1} \approx \frac{4^k I_{j,k} - I_{j-1,k}}{4^k - 1} = I_{j,k} + \frac{1}{4^k - 1} (I_{j,k} - I_{j-1,k})$$

- j : level of subdivision, $j+1$ has more intervals.
- k : level of integration, $k = 1$ is original trapezoid estimate [$O(h^2)$], $k = 2$ is improved [$O(h^4)$], etc.

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Romberg Integration

- For example, $j = 1, k = 1$ leads to

$$I_{1,1} = \frac{4I_{1,0} - I_{0,0}}{3} \approx \frac{4}{3}I\left(\frac{h_1}{2}\right) - \frac{1}{3}I(h_1)$$

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Example

- Consider the function:

$$f(x) = 0.2 + 25x - 200x^2 + 675x^3 - 900x^4 + 400x^5$$

- Integrate from $a = 0$ to $b = 0.8$
- Using the trapezoidal rule yields the following results:

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Example

- Trapezoid Rules:

				$k=0$	$k=1$
j	k	intervals	h	Integral	
	$j=0$	1	0.8	0.1728	}
	$j=1$	2	0.4	1.0688	
	$j=2$	4	0.2	1.4848	

$$I = \frac{4}{3}(1.0688) - \frac{1}{3}(0.1728) = 1.3674667 \quad (j=1, k=1)$$

Exact integral is 1.64053334

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Example

				$k=0$	$k=1$
j	k	segments	h	$O(h^2)$	$O(h^4)$
		1	0.8	0.1728	}
		2	0.4	1.0688	
		4	0.2	1.4848	

$$I = \frac{4}{3}(1.4848) - \frac{1}{3}(1.0688) = 1.62346667 \quad (j=2, k=1)$$

Exact integral is 1.64053334

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Example

		$k = 1$		$k = 2$	
j	k	segments	h	$O(h^2)$	$O(h^4)$
		1	0.8	0.1728	
2	0.4	1.0688	1.3674667		
4	0.2	1.4848	1.62346667		

$(j=2, k=2) \quad I = \frac{16}{15}(1.62346667) - \frac{1}{15}(1.3674667) = 1.64053334$

Exact integral is 1.64053334



Example

		$k = 1$		$k = 2$	$k = 3$	
j	k	segments	h	$O(h^2)$	$O(h^4)$	$O(h^6)$
		1	0.8	0.1728		
2	0.4	1.0688	1.3674667			
4	0.2	1.4848	1.62346667	1.64053334		



Example

- Better and better results can be obtained by continuing this

		$k = 3$				
j	segments	h	$O(h^2)$	$O(h^4)$	$O(h^6)$	$O(h^8)$
	1	0.8	0.1728			
	2	0.4	1.0688	1.3674667		
	4	0.2	1.4848	1.62346667	1.64053334	
	8	0.1	??	??	??	??

} $(j=3, k=3)$

$$I = \frac{64}{63}(\text{??}) - \frac{1}{63}(1.64053334) = \text{??}$$

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Romberg Integration

- Is this *that* significant?
- Consider the cost of computing the Trapezoid Rule for 1000 data points.
 - Refinement would lead to 2000 data points.
 - Implies an additional 1003 operations using the Recursive Trapezoid Rule.
 - Not to mention the 1000 (expensive) function evals.
 - Romberg Integration cost:
 - Three additional operations – no function evals!!!

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Higher-Order Polynomials

- Recall:

$$\int_{x_0}^{x_n} f(x)dx = \int_{x_0}^{x_0+m_1} p_{m_1}(x)dx + \int_{x_0+m_1}^{x_0+m_1+m_2} p_{m_2}(x)dx + \dots + \int_{x_n-m_n}^{x_n} p_{m_n}(x)dx$$

m	Polynomial	Formula	Error
1	linear	Trapezoid	$O(h^2)$
2	quadratic	Simpson's 1/3	$O(h^4)$
3	cubic	Simpson's 3/8	$O(h^4)$

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Simpson's 1/3 Rule

- If we use a 2nd order polynomial (need 3 points or 2 intervals):
 - Lagrange form. $\left(x_1 = \frac{x_0 + x_2}{2}\right)$

$$I = \int_{x_0}^{x_2} \left[\frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)} f(x_0) + \frac{(x-x_0)(x-x_2)}{(x_1-x_0)(x_1-x_2)} f(x_1) + \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)} f(x_2) \right] dx$$

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Simpson's 1/3 Rule

- **Requiring** equally-spaced intervals:

$$I = \int_{x_0}^{x_2} \left[\frac{(x-x_0-h)(x-x_0-2h)}{-h(-2h)} f(x_0) + \frac{(x-x_0)(x-x_0-2h)}{(h)(-h)} f(x_1) + \frac{(x-x_0)(x-x_0-h)}{(2h)(h)} f(x_2) \right] dx$$

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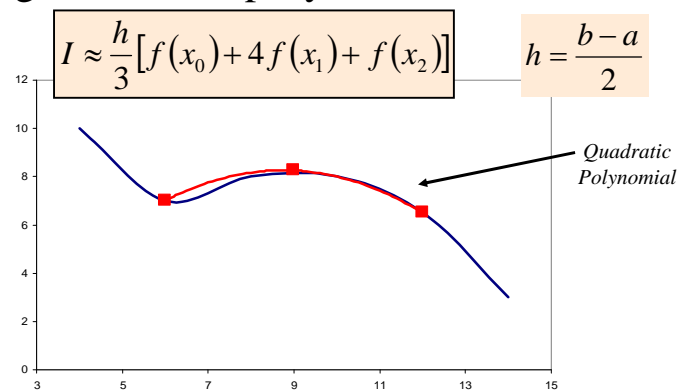
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Simpson's 1/3 Rule

- Integrate and simplify:



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Simpson's 1/3 Rule

- If we use $a = x_0$ and $b = x_2$, and $x_1 = (b+a)/2$

$$I \approx \underbrace{(b-a)}_{\text{width}} \underbrace{\frac{f(x_0) + 4f(x_1) + f(x_2)}{6}}_{\text{average height}}$$

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Simpson's 1/3 Rule

- Error for Simpson's 1/3 rule

$$E_i = -\frac{h^5}{90} f^{(4)}(\xi) = -\frac{(b-a)^5}{2880} f^{(4)}(\xi) \quad O(h^5)$$

$$h = \frac{b-a}{2}$$

\Rightarrow Integrates a cubic exactly: $f^{(4)}(\xi) = 0$

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Composite Simpson's 1/3 Rule

- As with Trapezoidal rule, can use multiple applications of Simpson's 1/3 rule.
- Need **even** number of intervals
 - An odd number of points are required.

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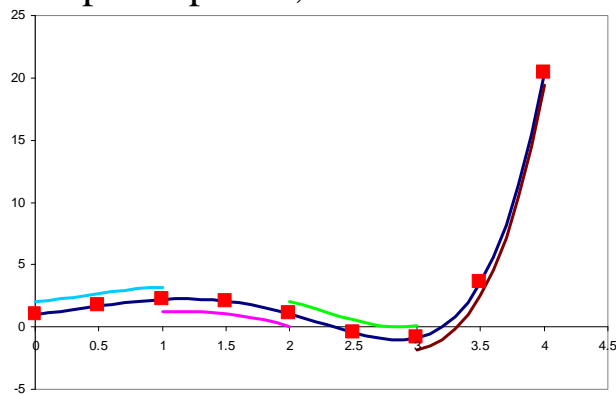
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Composite Simpson's 1/3 Rule

- Example: 9 points, 4 intervals



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Composite Simpson's 1/3 Rule

- As in composite trapezoid, break integral up into $n/2$ sub-integrals:

$$I = \int_{x_0}^{x_2} f(x)dx + \int_{x_2}^{x_4} f(x)dx + \dots + \int_{x_{n-2}}^{x_n} f(x)dx$$

- Substitute Simpson's 1/3 rule for each integral and collect terms.

$$I = (b-a) \frac{f(x_0) + 4 \sum_{i=1,3,5}^{n-1} f(x_i) + 2 \sum_{j=2,4,6}^{n-2} f(x_j) + f(x_n)}{3n}$$

$n+1$ data points, an odd number

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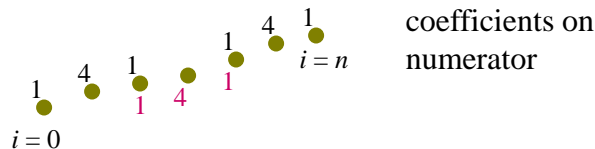
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Composite Simpson's 1/3 Rule

- Odd coefficients receive a weight of 4, even receive a weight of 2.
- Doesn't seem very fair, does it?



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Error Estimate

- The error can be estimated by:

$$E_a = \frac{nh^5}{180} \bar{f}^{(4)} = \frac{(b-a)h^4}{180} \bar{f}^{(4)} \quad O(h^4)$$

- If n is doubled, $h \rightarrow h/2$ and $E_a \rightarrow E_a/16$

$\bar{f}^{(4)}$ is the average 4th derivative



Example

- Integrate $f(x) = e^{-x^2}$ from $a = 0$ to $b = 2$.
- Use Simpson's 1/3 rule:

$$h = \frac{b-a}{2} = 1 \quad x_0 = a = 0 \quad x_1 = \frac{a+b}{2} = 1 \quad x_2 = b = 2$$

$$\begin{aligned} I &= \int_0^2 e^{-x^2} dx \approx \frac{1}{3} h [f(x_0) + 4f(x_1) + f(x_2)] \\ &= \frac{1}{3} [f(0) + 4f(1) + f(2)] \\ &= \frac{1}{3} (e^0 + 4e^{-1} + e^{-4}) = 0.82994 \end{aligned}$$



Example

- Error estimate: $E_t = -\frac{h^5}{90} f^{(4)}(\xi)$

- Where $h = b - a$ and $a < \xi < b$

- Don't know ξ

- use average value

$$E_t \approx E_a = -\frac{1^5}{90} \bar{f}^{(4)} = -\frac{1^5}{90} \frac{[f^{(4)}(x_0) + f^{(4)}(x_1) + f^{(4)}(x_2)]}{3}$$

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Another Example

- Let's look at the polynomial again:

$$f(x) = 0.2 + 25x - 200x^2 + 675x^3 - 900x^4 + 400x^5$$

- From $a = 0$ to $b = 0.8$

$$h = \frac{b-a}{2} = 0.4 \quad x_0 = a = 0 \quad x_1 = \frac{a+b}{2} = 0.4 \quad x_2 = b = 0.8$$

$$\begin{aligned} I &= \int_0^2 f(x) dx \approx \frac{1}{3} h [f(x_0) + 4f(x_1) + f(x_2)] \\ &= \frac{(0.4)}{3} [f(0) + 4f(0.4) + f(0.8)] \\ &= 1.36746667 \end{aligned}$$

Exact integral is 1.64053334

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Error

- Actual Error: (using the known exact value)

$$E = 1.64053334 - 1.36746667 = 0.27306666 \quad 16\%$$

- Estimate error: (if the exact value is not available)

$$E_t = -\frac{h^5}{90} f^{(4)}(\xi)$$

- Where $a < \xi < b$.

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Error

- Compute the fourth-derivative

$$f^{(4)}(x) = -21600 + 48000x$$

$$E_t \approx E_a = -\frac{0.4^5}{90} f^{(4)}(x_1) = -\frac{0.4^5}{90} f^{(4)}(0.4) = 0.27306667$$

middle point

- Matches actual error pretty well.

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Example Continued

- If we use 4 segments instead of 1: $h = \frac{b-a}{n} = 0.2$
 - $\mathbf{x} = [0.0 \ 0.2 \ 0.4 \ 0.6 \ 0.8]$
 - $f(0) = 0.2$ $f(0.2) = 1.288$ $f(0.4) = 2.456$
 - $f(0.6) = 3.464$ $f(0.8) = 0.232$

$$I = (b-a) \frac{f(x_0) + 4 \sum_{i=1,3,5}^{n-1} f(x_i) + 2 \sum_{j=2,4,6}^{n-2} f(x_j) + f(x_n)}{3n}$$

$$= (0.8-0) \frac{f(0) + 4f(0.2) + 2f(0.4) + 4f(0.6) + f(0.8)}{(3)(4)}$$

$$= 0.8 \frac{0.2 + 4(1.288 + 3.464) + 2(2.456) + 0.232}{12}$$

$$= 1.6234667 \qquad \text{Exact integral is } 1.64053334$$

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Error

- Actual Error: (using the known exact value)
 - $E = 1.64053334 - 1.6234667 = 0.01706667$ 1%
- Estimate error: (if the exact value is not available)

$$E_t \approx E_a = -\frac{0.2^5}{90} f^{(4)}(x_2) = -\frac{0.2^5}{90} f^{(4)}(0.4) = -0.0085$$

↑
middle point

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Error

- Actual is twice the estimated, why?
- Recall:

$$f^{(4)}(x) = -21600 + 48000x$$

$$\max_{x \in [0, 0.8]} \{ |f^{(4)}(x)| \} = |f^{(4)}(0)| = -21600$$
$$|f^{(4)}(0.4)| = 2400$$

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Error

- Rather than estimate, we can bound the absolute value of the error:

$$|E_a| = \left| -\frac{0.2^5}{90} f^{(4)}(\xi) \right| \leq \frac{0.2^5}{90} |f^{(4)}(0)| = 0.0768$$

- Five times the actual, but provides a safer error metric.

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Simpson's 1/3 Rule

- Simpson's 1/3 rule uses a 2nd order polynomial
 - need 3 points or 2 intervals
 - This implies we need an even number of intervals.
- What if you don't have an even number of intervals? Two choices:
 1. Use Simpson's 1/3 on all the segments except the last (or first) one, and use trapezoidal rule on the one left.
 - Pitfall - larger error on the segment using trapezoid
 2. Use Simpson's 3/8 rule.

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Simpson's 3/8 Rule

- Simpson's 3/8 rule uses a **third order polynomial**
 - need 3 intervals (4 data points)

$$f(x) \approx p_3(x) = a_0 + a_1x + a_2x^2 + a_3x^3$$

$$I = \int_{x_0}^{x_3} f(x)dx \approx \int_{x_0}^{x_3} p_3(x)dx$$

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Simpson's 3/8 Rule

- Determine a 's with Lagrange polynomial
- For evenly spaced points

$$I = \frac{3}{8}h[f(x_0) + 3f(x_1) + 3f(x_2) + f(x_3)]$$

$$h = \frac{b-a}{3}$$

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Error

- Same order as 1/3 Rule.
 - More function evaluations.
 - Interval width, h , is smaller.

$$E_t = -\frac{3}{80}h^5 f^{(4)}(\xi) \quad O(h^4)$$

- Integrates a cubic exactly:

$$\Rightarrow f^{(4)}(\xi) = 0$$

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Comparison

- Simpson's 1/3 rule and Simpson's 3/8 rule have the same order of error
 - $O(h^4)$
 - trapezoidal rule has an error of $O(h^2)$
- Simpson's 1/3 rule requires **even number** of segments.
- Simpson's 3/8 rule requires multiples of **three segments**.
- Both Simpson's methods require **evenly spaced** data points

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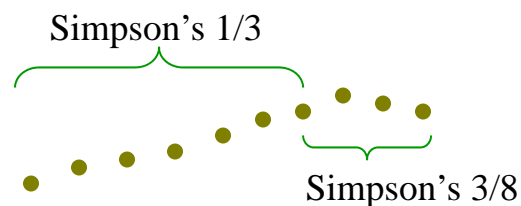
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Mixing Techniques

- $n = 10$ points \Rightarrow 9 intervals
 - First 6 intervals - Simpson's 1/3
 - Last 3 intervals - Simpson's 3/8



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Newton-Cotes Formulas

- We can examine even higher-order polynomials.
 - Simpson's 1/3 - 2nd order Lagrange (3 pts)
 - Simpson's 3/8 - 3rd order Lagrange (4 pts)
- Usually do not go higher.
- Use multiple segments.
 - But only where needed.

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Adaptive Simpson's Scheme

- Recall Simpson's 1/3 Rule:

$$I \approx \frac{h}{3} [f(x_0) + 4f(x_1) + f(x_2)]$$

- Where initially, we have $a=x_0$ and $b=x_2$.
- Subdividing the integral into two:

$$I \approx \frac{h}{6} [f(a) + 4f(x_1) + 2f(x_2) + 4f(x_3) + f(b)]$$

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Adaptive Simpson's Scheme

- We want to keep subdividing, until we reach a desired error tolerance, ϵ .
- Mathematically:

$$\left| \int_a^b f(x) dx - \left[\frac{h}{3} [f(a) + 4f(x_1) + f(b)] \right] \right| \leq \epsilon$$

$$\left| \int_a^b f(x) dx - \left[\frac{h}{6} [f(a) + 4f(x_1) + 2f(x_2) + 4f(x_3) + f(b)] \right] \right| \leq \epsilon$$

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Adaptive Simpson's Scheme

- This will be satisfied if:

$$\left| \int_a^c f(x) dx - \left[\frac{h}{6} [f(a) + 4f(x_1) + f(x_2)] \right] \right| \leq \frac{\epsilon}{2}, \text{ and}$$

$$\left| \int_c^b f(x) dx - \left[\frac{h}{6} [f(x_2) + 4f(x_3) + f(b)] \right] \right| \leq \frac{\epsilon}{2}, \text{ where}$$

$$c = x_2 = \frac{a+b}{2}$$

- The left and the right are within one-half of the error.

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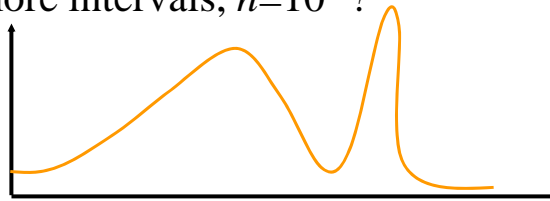
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Adaptive Simpson's Scheme

- Okay, now we have two separate intervals to integrate.
- What if one can be solved accurately with an $h=10^{-3}$, but the other requires many, many more intervals, $h=10^{-6}$?



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Adaptive Simpson's Scheme

- Adaptive Simpson's method provides a divide and conquer scheme until the appropriate error is satisfied everywhere.
- Very popular method in practice.
- Problem:
 - We do not know the exact value, and hence do not know the error.

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Adaptive Simpson's Scheme

- How do we know whether to continue to subdivide or terminate?

$$I \equiv \int_a^b f(x) dx = S(a,b) + E(a,b), \text{ where}$$

$$S(a,b) = \frac{b-a}{6} \left[f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right], \text{ and}$$

$$E(a,b) = -\frac{1}{90} \left(\frac{b-a}{2}\right)^5 f^{(4)}$$

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Adaptive Simpson's Scheme

- The first iteration can then be defined as:

$$I = S^{(1)} + E^{(1)}, \text{ where}$$

$$S^{(1)} = S(a,b), E^{(1)} = E(a,b)$$

- Subsequent subdivision can be defined as:

$$S^{(2)} = S(a,c) + S(c,b)$$

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Adaptive Simpson's Scheme

- Now, since

$$E^{(2)} = E(a, c) + E(c, b)$$

- We can solve for $E^{(2)}$ in terms of $E^{(1)}$.

$$\begin{aligned} E^{(2)} &= -\frac{1}{90} \left(\frac{h/2}{2} \right)^5 f^{(4)} - \frac{1}{90} \left(\frac{h/2}{2} \right)^5 f^{(4)} \\ &= \left(\frac{1}{2^4} \right) - \frac{1}{90} \left(\frac{h}{2} \right)^5 f^{(4)} = \frac{1}{16} E^{(1)} \end{aligned}$$

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Adaptive Simpson's Scheme

- Finally, using the identity:

$$I = S^{(1)} + E^{(1)} = S^{(2)} + E^{(2)}$$

- We have:

$$S^{(2)} - S^{(1)} = E^{(1)} - E^{(2)} = 15E^{(2)}$$

- Plugging into our definition:

$$I = S^{(2)} + E^{(2)} = S^{(2)} + \frac{1}{15} (S^{(2)} - S^{(1)})$$

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Adaptive Simpson's Scheme

- Our error criteria is thus:

$$\left| I - S^{(2)} \right| = \left| \frac{1}{15} (S^{(2)} - S^{(1)}) \right| \leq \varepsilon$$

- Simplifying leads to the termination formula:

$$\left| (S^{(2)} - S^{(1)}) \right| \leq 15\varepsilon$$

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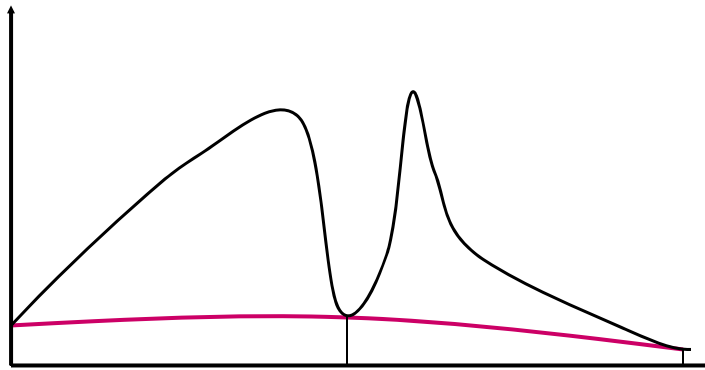
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Adaptive Simpson's Scheme

- What happens graphically:



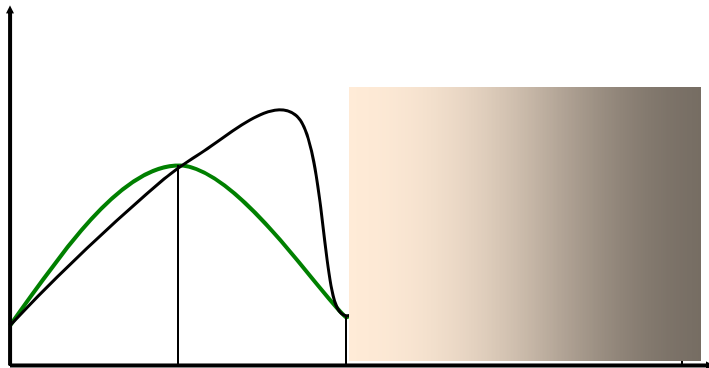
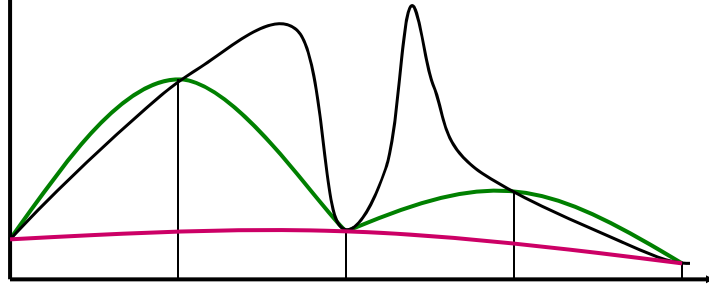
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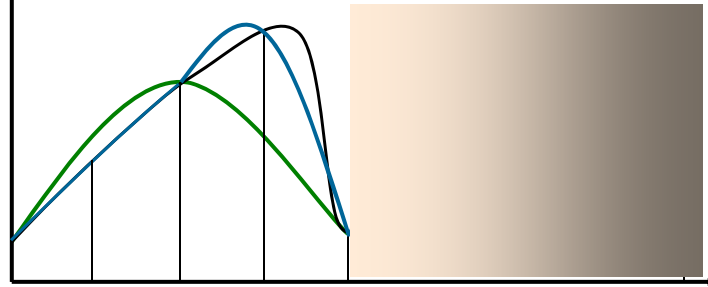


$$|S_2 - S_1| \geq 15\epsilon \rightarrow \textit{subdivide}$$





$$|S_2 - S_1| \geq 15 \frac{\epsilon}{2} \rightarrow \textit{subdivide}$$



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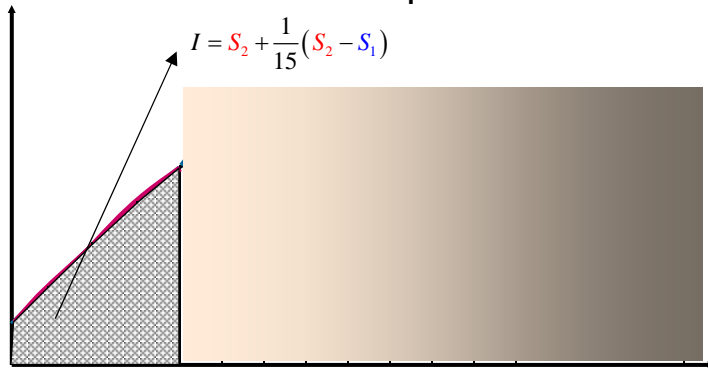
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$$|S_2 - S_1| \leq 15 \frac{\epsilon}{4} \rightarrow \textit{done}$$

$$I = S_2 + \frac{1}{15}(S_2 - S_1)$$

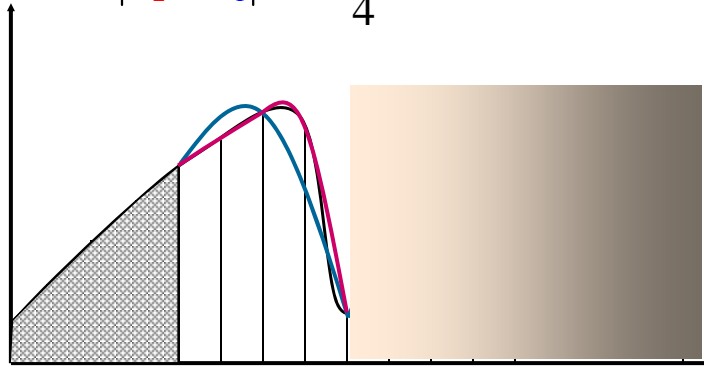


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$$|S_2 - S_1| \geq 15 \frac{\epsilon}{4} \rightarrow \textit{subdivide}$$

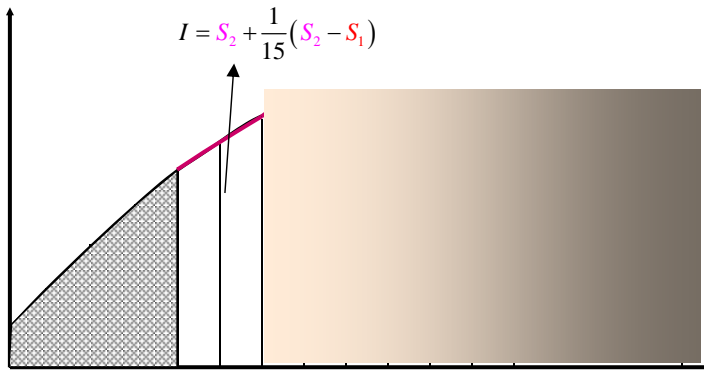


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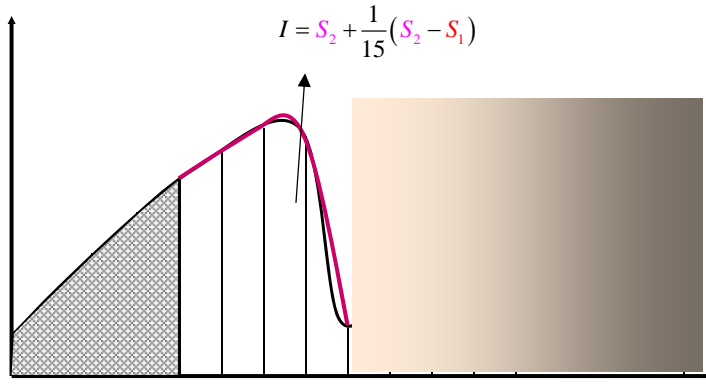
$$I = S_2 + \frac{1}{15}(S_2 - S_1)$$



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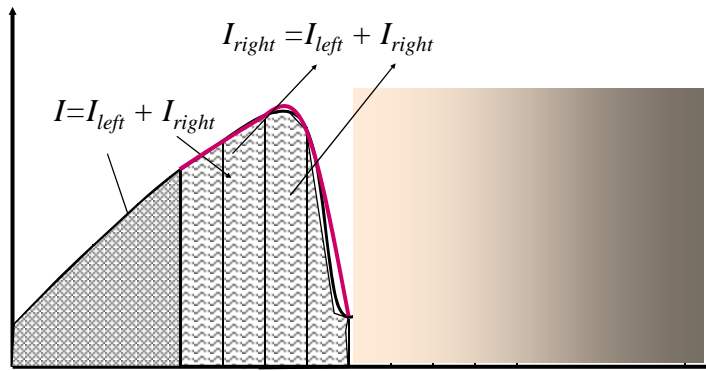
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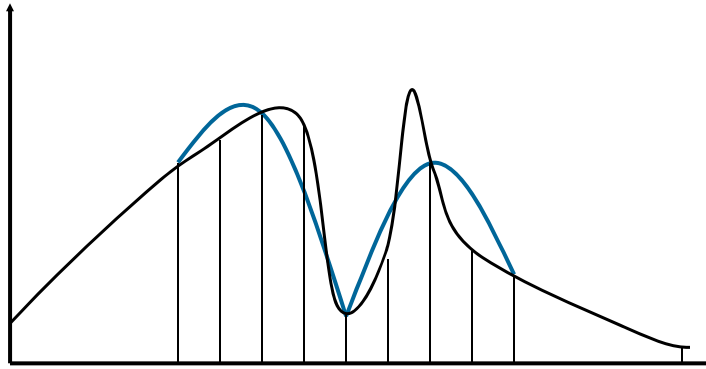
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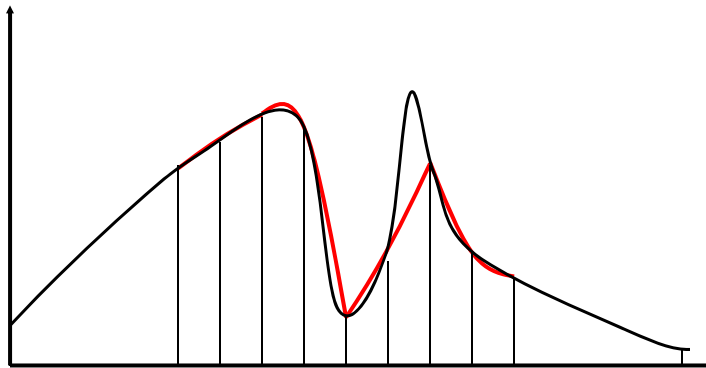
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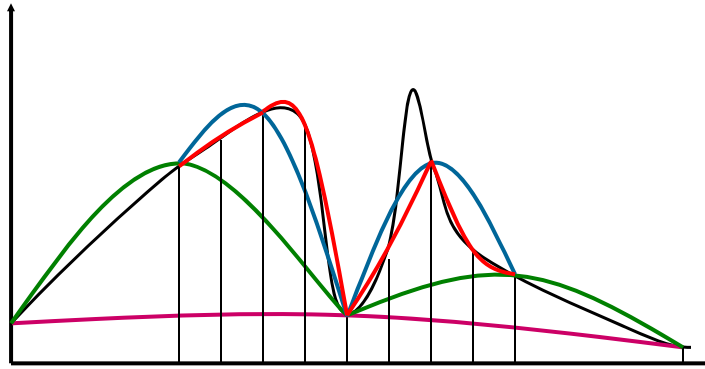
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Adaptive Simpson's Scheme

- We gradually capture the difficult spots.



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Adaptive Simpson's Code

- Simple Recursive Program

```
static const int m_nMaximum_Divisions = 1000;
Real IntegrationSimpson( const Real (*f)(Real x), const Real start, const Real end, const Real
                        error_tolerance, int &level )
{
    level += 1;
    Real h = (end - start);
    Real midpoint = (start + end) / 2.0;
    Real f_start = f(start);
    Real f_end = f(end);
    Real f_mid = f(midpoint);
    oneLevel = h*(f_start + 4.0*f_mid + f_end) / 6.0;
    Real leftMidpoint = (start+ midpoint) / 2.0;
    Real rightMidpoint = (end+ midpoint) / 2.0;
    Real f_midLeft = f(leftMidpoint);
    Real f_midRight = f(rightMidpoint);
    twoLevel = h*(f_start + 4.0*f_midLeft + 2.0*f_mid + 4.0*f_midRight + f_end) / 12.0;
    if( level >= m_nMax_Divisions ) // Terminate the process, converging too slow
        return twoLevel;
}
```

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Adaptive Simpson's Code

```
if( absf( twoLevel - oneLevel) < 15.0*error_tolerance) // Desired solution reached
    return twoLevel + (twoLevel-oneLevel) / 15.0;
//
// Otherwise, split the interval in two and recursively evaluate each half.
//
leftIntegral = IntegrationSimpson(f, start, midpoint, error_tolerance/2.0, level);
rightIntegral = IntegrationSimpson(f, midpoint, end, error_tolerance/2.0, level);
return leftIntegral + rightIntegral;
}
```

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Gaussian Quadrature

- Idea is that if we evaluate the function at certain points, and sum with certain weights, we will get a more accurate integral
- Evaluation points and weights are pre-computed and tabulated
- Basic form:
$$I = \int_{-1}^1 f(x)dx \approx \sum_{i=1}^n c_i f(x_i)$$

c_i : weighting factors

x_i : sampling points selected optimally



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Guassain Quadrature

- Note that the interval is between -1 and 1
- For other intervals, a change of variables is used to transfer the problem so that it utilizes the interval $[-1, 1]$
- This is a linear transform, such that for $t \in [a, b]$:

$$\int_a^b f(t) dt$$

- We have for $x \in [-1, 1]$:

$$t = \frac{(b-a)x + b + a}{2}$$



$$x = \frac{2t - b - a}{b - a}$$

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Guassain Quadrature

- As $t = a \Rightarrow x = -1$
- As $t = b \Rightarrow x = 1$

$$dt = \frac{(b-a)}{2} dx$$

$$f(t) = f\left(\frac{(b-a)x + b + a}{2}\right)$$

$$\int_a^b f(t) dt = \frac{(b-a)}{2} \int_{-1}^1 f\left(\frac{(b-a)x + b + a}{2}\right) dx$$

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Guassian Quadrature

- Basic form of Gaussian quadrature:

$$I = \int_{-1}^1 f(x)dx \approx \sum_{i=1}^n c_i f(x_i)$$

- For $n=2$, we have:

$$I \approx c_1 f(x_1) + c_2 f(x_2)$$

- This leads to 4 unknowns: c_1 , c_2 , x_1 , and x_2
 - two unknown weights (c_1 , c_2)
 - two unknown sampling points (x_1 , x_2)

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Guassian Quadrature

- What we need now, are four known values for the equation.
- If we had these, we could then attempt to solve for the four unknowns.
- Let's make it work for polynomials!!!

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Guassian Quadrature

- In particular, let's look at these simple polynomials:
 - Constant
 - $f(x)=1$
 - Linear
 - $f(x)=x$
 - Quadratic
 - $f(x)=x^2$
 - Cubic
 - $f(x)=x^3$

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Guassian Quadrature

- Recalling the formula: $I \approx c_1 f(x_1) + c_2 f(x_2)$
 - Constant
 - $f(x)=1$ $\int_{-1}^1 1 dx = 2 = c_1 f(x_1) + c_2 f(x_2) = c_1 + c_2$
 - Linear
 - $f(x)=x$ $\int_{-1}^1 x dx = 0 = c_1 f(x_1) + c_2 f(x_2) = c_1 x_1 + c_2 x_2$
 - Quadratic
 - $f(x)=x^2$ $\int_{-1}^1 x^2 dx = \frac{2}{3} = c_1 f(x_1) + c_2 f(x_2) = c_1 x_1^2 + c_2 x_2^2$
 - Cubic
 - $f(x)=x^3$ $\int_{-1}^1 x^3 dx = 0 = c_1 f(x_1) + c_2 f(x_2) = c_1 x_1^3 + c_2 x_2^3$

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Guassian Quadrature

- We can now solve for our unknowns:
 - *Note, this is not an easy problem and will not be covered in this class.*

$$c_1 = c_2 = 1$$

$$x_1 = -\frac{1}{\sqrt{3}} = -0.577$$

$$x_2 = \frac{1}{\sqrt{3}} = 0.577$$

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Guassian Quadrature

- This yields the two point **Gauss-Legendre** formula

$$I \approx f\left(-\frac{1}{\sqrt{3}}\right) + f\left(\frac{1}{\sqrt{3}}\right)$$

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Guassian Quadrature

- This is **exact** for **all** polynomials up to and including degree 3 (cubics).

$$\begin{aligned}\int_{-1}^1 (ax^3 + bx^2 + cx + d) dx &= a \int_{-1}^1 x^3 dx + b \int_{-1}^1 x^2 dx + c \int_{-1}^1 x dx + d \int_{-1}^1 dx \\ &= a \left(\left(\frac{-1}{\sqrt{3}} \right)^3 + \left(\frac{1}{\sqrt{3}} \right)^3 \right) + b \left(\left(\frac{-1}{\sqrt{3}} \right)^2 + \left(\frac{1}{\sqrt{3}} \right)^2 \right) + c \left(\left(\frac{-1}{\sqrt{3}} \right) + \left(\frac{1}{\sqrt{3}} \right) \right) + d(1+1) \\ &= \left(ax^3 + bx^2 + cx + d \right) \Big|_{-\frac{1}{\sqrt{3}}}^{\frac{1}{\sqrt{3}}}\end{aligned}$$

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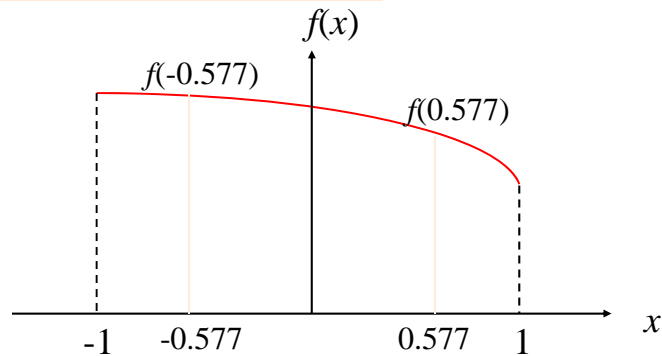
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Guassian Quadrature

$$\int_{-1}^1 f(x) dx \approx f(-0.577) + f(0.577)$$



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Example

- Integrate $f(x)$ from $a = 0$ to $b = 0.8$

$$f(x) = 0.2 + 25x - 200x^2 + 675x^3 - 900x^4 + 400x^5$$

- Transform from $[0, 0.8]$ to $[-1, 1]$

$$\int_a^b f(t) dt = \frac{(b-a)}{2} \int_{-1}^1 f\left(\frac{(b-a)x + b + a}{2}\right) dx$$

$$\begin{aligned} \Rightarrow I &= \int_0^{0.8} f(x) dx = \frac{(0.8-0)}{2} \int_{-1}^1 f\left(\frac{(0.8-0)t + 0.8 + 0}{2}\right) dt \\ &= 0.4 \int_{-1}^1 f(0.4t + 0.4) dt \end{aligned}$$

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Example

- Solving

$$\begin{aligned} I &= 0.4 \int_{-1}^1 f(0.4t + 0.4) dt \\ &= 0.4 \int_{-1}^1 \left[0.2 + 25(0.4t - 0.4) - 200(0.4t - 0.4)^2 \right. \\ &\quad \left. + 675(0.4t - 0.4)^3 - 900(0.4t - 0.4)^4 + 400(0.4t - 0.4)^5 \right] dt \end{aligned}$$

- And substituting for the 2-point formula:

$$I = 0.4 \int_{-1}^1 f(t) dt \quad t = \pm 1/\sqrt{3}$$

$$I \approx 0.51674055 + 1.30583723 = 1.82257778$$

Exact integral is **1.64053334**

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Higher-order Gaussian Quadrature

- Recall the basic form:

$$I = \int_{-1}^1 f(x) dx \approx \sum_{i=1}^n c_i f(x_i)$$

- Let's look at $n=3$.

$$I \approx c_1 f(x_1) + c_2 f(x_2) + c_3 f(x_3)$$

- We now have 6 unknowns: $c_1, c_2, c_3, x_1, x_2,$ and x_3
 - three unknown weights (c_1, c_2, c_3)
 - three unknown sampling points (x_1, x_2, x_3)

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Use 6 equations - constant, linear, quadratic, cubic, 4th order and 5th order to find those unknowns

$$\int_{-1}^1 1 dx = 2 = c_1 f(x_1) + c_2 f(x_2) + c_3 f(x_3) = c_1 + c_2 + c_3$$

$$\int_{-1}^1 x dx = 0 = c_1 f(x_1) + c_2 f(x_2) + c_3 f(x_3) = c_1 x_1 + c_2 x_2 + c_3 x_3$$

$$\int_{-1}^1 x^2 dx = \frac{2}{3} = c_1 f(x_1) + c_2 f(x_2) + c_3 f(x_3) = c_1 x_1^2 + c_2 x_2^2 + c_3 x_3^2$$

$$\int_{-1}^1 x^3 dx = 0 = c_1 f(x_1) + c_2 f(x_2) + c_3 f(x_3) = c_1 x_1^3 + c_2 x_2^3 + c_3 x_3^3$$

$$\int_{-1}^1 x^4 dx = \frac{2}{5} = c_1 f(x_1) + c_2 f(x_2) + c_3 f(x_3) = c_1 x_1^4 + c_2 x_2^4 + c_3 x_3^4$$

$$\int_{-1}^1 x^5 dx = 0 = c_1 f(x_1) + c_2 f(x_2) + c_3 f(x_3) = c_1 x_1^5 + c_2 x_2^5 + c_3 x_3^5$$

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Higher-order Gaussian Quadrature

- Can solve these equations (or have some one smarter than us, like Gauss solve them).

$$\begin{array}{ccc} c_1 = 5/9 & c_2 = 8/9 & c_3 = 5/9 \\ x_1 = -\sqrt{3/5} = -0.77459669 & x_2 = 0 & x_3 = \sqrt{3/5} = 0.77459669 \end{array}$$

- Produces the three point Gauss-Legendre formula

$$I \approx c_1 f(x_1) + c_2 f(x_2) + c_3 f(x_3)$$

- Exact for polynomials up to and including **degree 5** (because using 5th degree polynomial)

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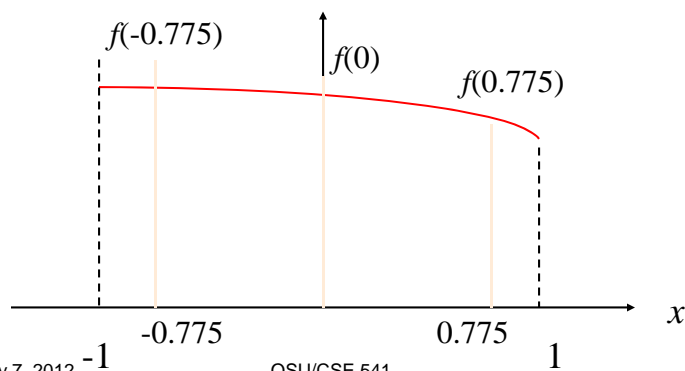
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Higher-order Gaussian Quadrature

$$\int_{-1}^1 f(x) dx \approx \frac{5}{9} f(-0.775) + \frac{8}{9} f(0.0) + \frac{5}{9} f(0.775)$$



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Example

$$f(x) = 0.2 + 25x - 200x^2 + 675x^3 - 900x^4 + 400x^5$$

Integrate from $a = 0$ to $b = 0.8$

Transform from $[0, 0.8]$ to $[-1, 1]$

$$I = \int_0^{0.8} f(x) dx$$

$$= \int_{-1}^1 \left[0.2 + 25(0.4t - 0.4) - 200(0.4t - 0.4)^2 + 675(0.4t - 0.4)^3 - 900(0.4t - 0.4)^4 + 400(0.4t - 0.4)^5 \right] dt$$

replace -0.4 with +0.4

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Example

- Using the 3-point Gauss-Legendre formula:

$$I \approx \frac{5}{9} f\left(-\sqrt{\frac{3}{5}}\right) + \frac{8}{9} f(0) + \frac{5}{9} f\left(\sqrt{\frac{3}{5}}\right)$$

Substitute into the transform equation and get

$$I \approx 0.281301290 + 0.873244444 + 0.485987599$$

$$= 1.640533334$$

Exact integral is **1.64053334**

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Gaussian Quadrature

Can develop higher order Gauss-Legendre forms using

$$I \approx c_1 f(x_1) + c_2 f(x_2) + \dots + c_n f(x_n)$$

Values for c 's and x 's are tabulated

Use the same transformation to map interval onto $[-1, 1]$

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$$I = \int_{-1}^1 f(x) dx \approx c_1 f(x_1) + c_2 f(x_2) + \dots + c_n f(x_n)$$

n	2	3	4	5	6
c_i	1.0	0.5555555556	0.3478548451	0.2369268850	0.1713245
	1.0	0.8888888889	0.6521451549	0.4786286705	0.3607616
		0.5555555556	0.6521451549	0.5688888889	0.4679139
			0.3478548451	0.4786286705	0.4679139
				0.2369268850	0.3607616
					0.1713245
	-0.5773502692	-0.7745966692	-0.8611363116	-0.9061798459	-0.932469514
x_i	0.5773502692	0.0000000000	-0.3399810436	-0.5384693101	-0.661209386
		0.7745966692	0.3399810436	0.0000000000	-0.238619186
			0.8611363116	0.5384693101	0.238619186
				0.9061798459	0.661209386
					0.932469514

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Gaussian Quadrature

- Requires function evaluations at non-uniformly spaced points within the integration interval
 - not appropriate for cases where the function is unknown
 - not suited for dealing with tabulated data that appear in many engineering problems
- If the function is known, its efficiency can be a decided advantage

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Gaussian Quadrature

- Problems:
 - If we add more data points, like doubling the number of sample points.

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