

Lecture # 22

The Laplace equation

- If u is a steady state ~~temp~~ (independent of time) you solve or diffusion equations u will obtain

$$u_{xx} = 0 \quad \text{in 1-D}$$

$$\Delta u = 0 \quad \text{in n-D}$$

when if $u = u(x_1, \dots, x_n)$, then $\Delta u = \sum_{i=1}^n \partial_{x_i}^2 u$,

since both u_t and u_{tt} are zero. A

Definition: If $\Delta u = 0$ then u is called harmonic.

- ~~The~~ ~~the~~ inhomogeneous Laplace equation takes the name of Poisson equation

$$\Delta u = f$$

- The Boundary Value Problem that one solves is:

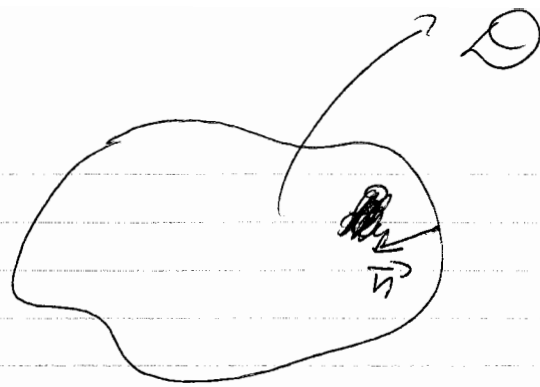
Given a domain D find u s.t.

$$\begin{cases} \Delta u = f & \text{in } D \\ u = h \text{ or } \frac{\partial u}{\partial n} = h \text{ or } \frac{\partial u}{\partial n} + au = h & \text{in } \partial D \end{cases}$$

Darboux

Robin

where $\frac{\partial}{\partial n}$ is the normal derivative to the boundary ∂D of D .



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$$\frac{\partial u}{\partial \vec{n}} = \langle \nabla u, \vec{n} \rangle$$

The 1-D case is completely trivial since

$$u_{xx} = 0 \text{ is solved by}$$

$$gives the solution \quad u(x) = Ax + B$$

and A and B are determined by the boundary conditions.

Also

$$u_{xx} = f \text{ is solved by integrating twice.}$$

So we will consider the problem of least in 2-D.

Maximum Principle: ~~is solved by~~

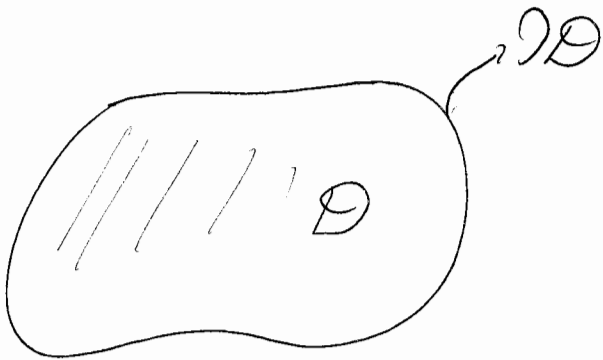
Let D be a connected bounded open set. Let u be an harmonic function in D and continuous all the way to ∂D . Then

$$a) \quad \max_{\overline{D}} u = \max_{\partial D} u \quad (\min_{\overline{D}} u = \min_{\partial D} u)$$

If D is also connected and open, then

b) There are no max or min points in D unless $u \equiv \text{const.}$

Proof: Assume for simplicity u on in \mathbb{R}^2



$$\partial \cup \bar{D} = \bar{D}$$

Remember the proof for diffusion equation:

If there is a point P in D s.t. $u(P) = \max_{\bar{D}} u$
 then $\nabla u = 0$ and $u_{xx} \leq 0, u_{yy} \leq 0$

$$\Delta u = u_{xx} + u_{yy} \leq 0$$

If we had < 0 then we would get the contradiction. But not then yet. So like for diffusion eq. let's modify a bit our function u .
 Pick $\epsilon > 0$ small and define

$$v(x,y) = u(x,y) + \epsilon |(x,y)|^2$$

Then v is continuous in \bar{D} , \bar{D} is closed and bounded \Rightarrow then exists $\max_{\bar{D}} v$ and $\min_{\bar{D}} v$

let's $P = \max_{\bar{D}} v$. Suppose P in D then

$$\nabla v = 0 \quad v_{xx}, v_{yy} \leq 0 \quad (\text{D})$$

$$v_{xx} = u_{xx} + \epsilon (x^2 + y^2)_{xx} = u_{xx} + 2\epsilon$$

$$v_{yy} = u_{yy} + 2\epsilon$$

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so
$$v_{xx} + v_{yy} = u_{xx} + u_{yy} + 2\varepsilon = 2\varepsilon > 0$$
 (4)

Clearly (4) and (3) give a contradiction.

So P has to be on ∂D .

Now in general for any (x, y) in \bar{D}

$$u(x, y) \leq v(x, y) \leq v(P) = u(P) + \varepsilon |P|^2 < u(P) + \varepsilon l^2$$

when $l \leq \frac{1}{\varepsilon} \max_{\partial D} u \leq \max_{\partial D} u + \varepsilon l^2$

by letting $\varepsilon \rightarrow 0$

$$\max_{\bar{D}} u \leq \max_{\partial D} u$$

\geq
trivial.

This gives the first part of Max. principle. Part b) will be proved next time.

Remark: For part a) the assumption " D connected" is not necessary.

Proof of Uniqueness of Dirichlet Problem on bounded domain

Assume that the problem
$$\begin{cases} \Delta u = f & \text{in } D \\ u|_{\partial D} = h \end{cases}$$
 has two solutions u and v ,

Then $w = u - v$ solves the ~~the~~ problem

$$\begin{cases} \Delta w = 0 & \text{in } \Omega \\ w|_{\partial\Omega} = 0 \end{cases}$$

If Ω is bounded then

$$\max_{\overline{\Omega}} w = \max_{\partial\Omega} w = 0 \Rightarrow \max_{\Omega} w = 0$$

similarly $\min_{\overline{\Omega}} w = \min_{\partial\Omega} w = 0 \Rightarrow \min_{\Omega} w = 0$

$$0 \leq w \leq 0 \Leftrightarrow w = 0 \Leftrightarrow v = u!$$

Here is a different way of proving uniqueness: Energy method
Consider the Dirichlet problem

$$\begin{cases} \Delta u = f \\ u|_{\partial\Omega} = h \end{cases}$$

$\partial\Omega$ smooth enough for divergence theorem

$w = u - v$, u, v two sol.

~~$$\int_{\Omega} \nabla u \cdot \nabla u = 0 \Rightarrow \int_{\Omega} \nabla(u+v) \cdot \nabla(u+v) = 0$$~~

~~$$= \int_{\Omega} |\nabla(u+v)|^2 = \int_{\Omega} (\nabla u)^2 + \int_{\Omega} (\nabla v)^2 + 2 \int_{\Omega} \nabla u \cdot \nabla v$$~~

$$\begin{cases} \Delta w = 0 \\ w|_{\partial\Omega} = 0 \end{cases}$$

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Clearly $w \Delta w = 0$. Consider the vector

$$\begin{aligned} w \nabla w &= w (\partial_x w, \partial_y w) \\ &= (w \partial_x w, w \partial_y w) \end{aligned}$$

By divergence theorem

$$\int_D \operatorname{div} \vec{f} \, dx = \int_{\partial D} \vec{f} \cdot \vec{n} \, ds$$

$$\operatorname{div}(w \nabla w) = \nabla \cdot (w \nabla w) = \nabla w \cdot \nabla w + w \Delta w$$

So

$$\begin{aligned} \int_D |\nabla w|^2 \, dx + \int_D w \Delta w \, dx &= \int_{\partial D} w \cdot \nabla w \cdot \vec{n} \, ds \\ &= \int_{\partial D} w \frac{\partial w}{\partial \vec{n}} \, ds \end{aligned}$$

$$\text{So } |\nabla w| \equiv 0 \Rightarrow \nabla w = 0 \quad \text{on } \partial D \Rightarrow w = \text{const}$$

$$\text{but } w|_{\partial D} = 0 \Rightarrow w \equiv 0!$$

Invariance of Laplacian:

Assume we have a change of variables in \mathbb{R}^2

$$(x, y) \xrightarrow{A} (x', y')$$

We say that Δ is "invariant" under the transformation A

is

$$\Delta u_{xx} + \Delta u_{yy} = \Delta u_{x'x'} + \Delta u_{y'y'}$$

Theorem: Δ is invariant under rotations and translations

Proof:

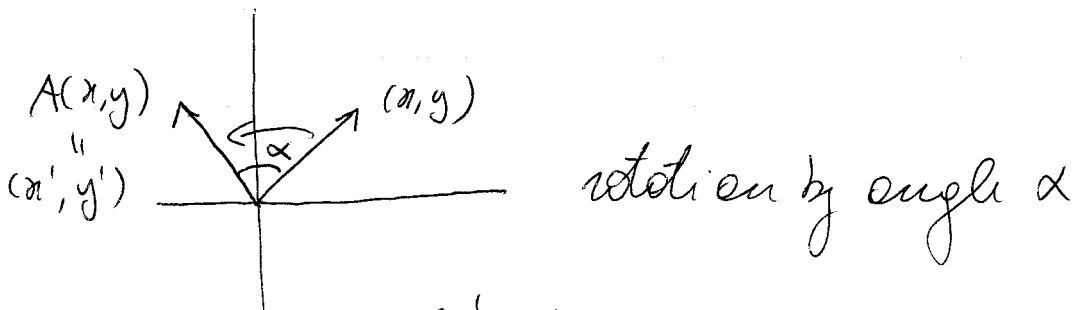
a) Invariant under translations: $(x, y) \rightarrow (x+a, y+b)$

$$A(x, y) = (x+a, y+b) \Rightarrow \begin{aligned} x' &= x+a \\ y' &= y+b \end{aligned}$$

$$\partial_{x'x'} = \partial_{xx}$$

$$\partial_{y'y'} = \partial_{yy}$$

b) Invariant under rotation:



$$x' = x \cos \alpha + y \sin \alpha$$

$$y' = -x \sin \alpha + y \cos \alpha$$

$$u_{x''} = u_{x'} \cos \alpha + u_{y'} \sin \alpha$$

$$u_{y''} = -u_{x'} \sin \alpha + u_{y'} \cos \alpha$$

$$\begin{aligned} u_{x''x''} &= u_{x'x'} \cos^2 \alpha + u_{x'y'} \cos \alpha \sin \alpha \\ &\quad + u_{x'y'} \sin \alpha \cos \alpha + u_{y'y'} \sin^2 \alpha \end{aligned}$$

$$u_{y^*y^*} = + u_{x'x'} \sin^2 \alpha - u_{x'y'} \sin \alpha \cos \alpha$$

$$+ u_{y'x'} \sin \alpha \cos \alpha + u_{y'y'} \cos^2 \alpha$$

$$u_{x^*x^*} + u_{y^*y^*} = u_{x'x'} (\cos^2 \alpha + \sin^2 \alpha) + 2u_{x'y'} \cos \alpha \sin \alpha - 2u_{x'y'} \sin \alpha \cos \alpha$$

$$+ u_{y'y'} (\cos^2 \alpha + \sin^2 \alpha) = u_{x'x'} + u_{y'y'}$$

Remark: Invariance by rotation should indicate that in polar coordinate Δ is simple

Laplace in polar coordinates

$$x = r \cos \theta$$

$$y = r \sin \theta$$

~~From the chain rule~~ From the chain rule the Jacobian matrix is

$$J = \begin{pmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{pmatrix} = \begin{pmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{pmatrix}$$

The inverse is

$$J^{-1} = \begin{pmatrix} \frac{\partial r}{\partial x} & \frac{\partial r}{\partial y} \\ \frac{\partial \theta}{\partial x} & \frac{\partial \theta}{\partial y} \end{pmatrix} = \begin{pmatrix} \cos \theta & \frac{-\sin \theta}{r} \\ \sin \theta & \frac{\cos \theta}{r} \end{pmatrix}$$

Now if $u = u(r(x,y), \theta(x,y))$

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial x}$$

$$\frac{\partial u}{\partial y} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial y}$$

$$\begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix} = \begin{pmatrix} \frac{\partial r}{\partial x} & \frac{\partial \theta}{\partial x} \\ \frac{\partial r}{\partial y} & \frac{\partial \theta}{\partial y} \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial \theta} \end{pmatrix} = J^{-1} \begin{pmatrix} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial \theta} \end{pmatrix}$$

So we obtain
$$\begin{cases} \frac{\partial}{\partial x} = \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial y} = \sin \theta \frac{\partial}{\partial r} + \frac{\cos \theta}{r} \frac{\partial}{\partial \theta} \end{cases}$$

$$\frac{\partial^2}{\partial x^2} = \left[\cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right]^2 = \cos^2 \theta \frac{\partial^2}{\partial r^2} + \frac{\sin^2 \theta}{r^2} \frac{\partial^2}{\partial \theta^2}$$

$$- \cos \theta \frac{\partial}{\partial r} \left(\frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \left[\cos \theta \frac{\partial}{\partial r} \right]$$

$$= \cos^2 \theta \frac{\partial^2}{\partial r^2} + \frac{\sin^2 \theta}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\cos \theta \sin \theta}{r^2} \frac{\partial}{\partial \theta}$$

$$+ \frac{\sin^2 \theta}{r} \frac{\partial}{\partial r}$$

$$\frac{\partial^2}{\partial y^2} = \left[\sin \theta \frac{\partial}{\partial r} + \frac{\cos \theta}{r} \frac{\partial}{\partial \theta} \right]^2$$

$$= \sin^2 \frac{\partial^2}{\partial r^2} + \frac{\cos^2}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\sin \theta \cos \theta}{r^2} \frac{\partial^2}{\partial r \partial \theta}$$

$$+ \frac{\cos \theta \sin \theta}{r} \frac{\partial}{\partial r}$$

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} = \frac{\partial^2}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{1}{r} \frac{\partial}{\partial r}$$

Search for radially-symmetric harmonic functions

We are looking for a harmonic and depending only on $r \Rightarrow u(x, y) = u(|(x, y)|) = u(r)$

then we solve

$$r \cdot \left[\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} \right] = 0 \quad \text{since } \frac{\partial u}{\partial \theta} = 0$$

\Downarrow

$$(r u_r)_r = 0 \quad \Leftrightarrow \quad r u_r = C_0 \quad \Leftrightarrow \quad u_r = \frac{C_0}{r}$$

$$\Leftrightarrow u(r) = C_0 \log r + C_1$$

So in 2-D a radially symmetric harmonic function

is of the form

$$u(x,y) = C_0 \log(x^2+y^2)^{\frac{1}{2}} + C_1$$

for $(x,y) \neq 0$!

Invariance in 3-D:

A similar analysis can be done in 3D

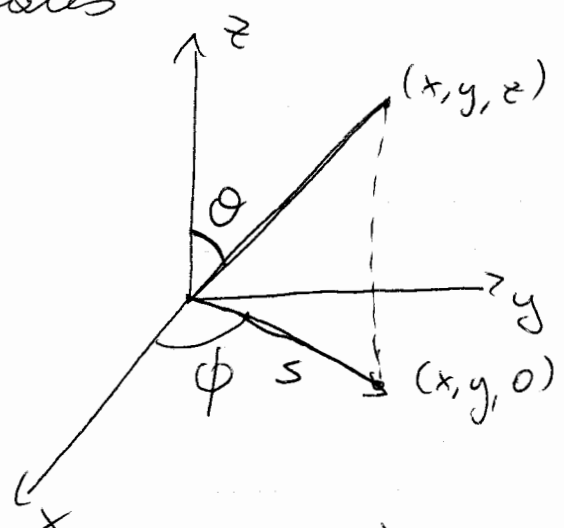
- Invariance under translation and rotation
- The Δ in spherical coordinates

$$x = s \cos \phi$$

$$y = s \sin \phi$$

$$z = r \cos \theta$$

$$s = r \sin \theta$$



$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2}$$

A radially symmetric harmonic function in \mathbb{R}^3

Let's the form $r^2 [u_{rr} + \frac{2}{r} u_r] = 0$

where $r = (x^2 + y^2 + z^2)^{\frac{1}{2}}$.

$$(r^2 u_r)_r = 2r u_r + r^2 u_{rr} \Rightarrow u = -C_1 r^{-1} + C_2$$