

# Texture Mapping:

CSE 681

# Texture Mapping

Visual complexity on demand

Vary display properties over object

Visible **pixel** maps to **location** on object

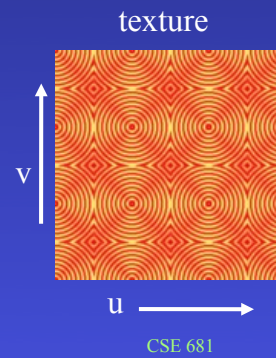
**Location** on object  
used to **lookup** display **attributes**

Or  
as **function parameters** to generate **attributes**

## 2D Texture Mapping

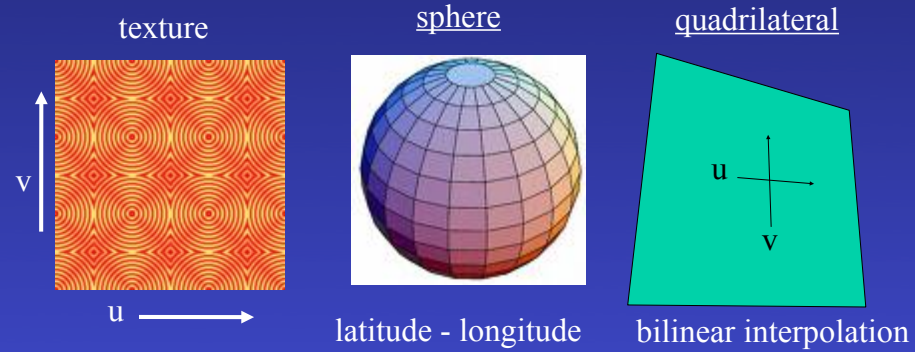
Usually a 2D rectangular image or function

Parameterize using  $(u,v)$  texture coordinates



# 2D Texture Mapping

Need to parameterize surface similar to texture



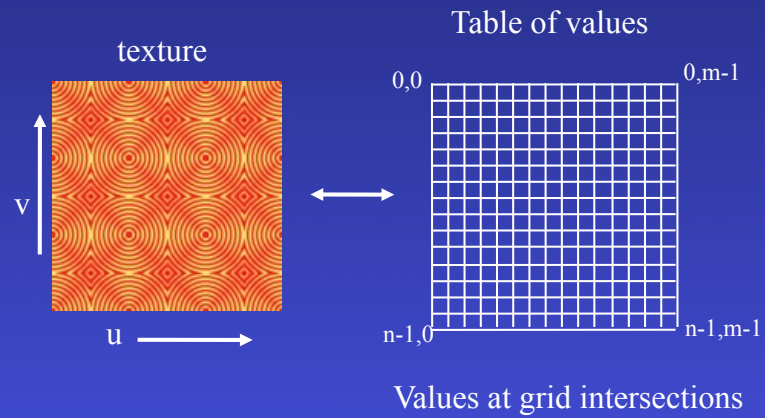
Also - cylindrical is a common mapping

CSE 681

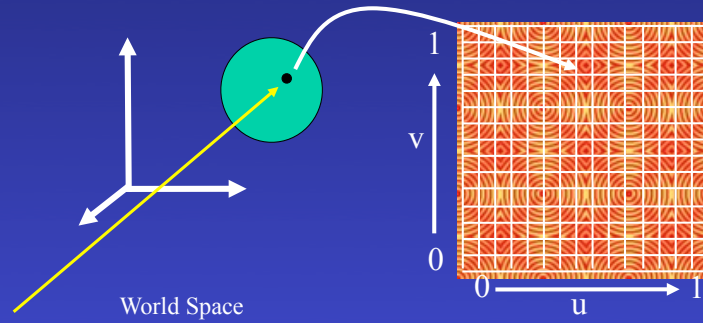
Simple examples - sphere and quadrilateral

More interesting - triangle mesh - not dealt with here

# Texture as table of values

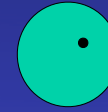
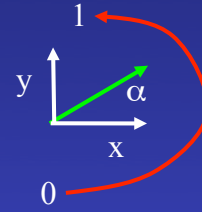
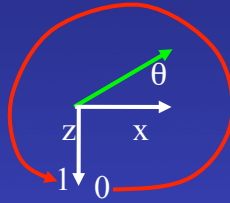


# For sphere Texture Map Coordinates



Map  $(x,y,z)$  to  $u,v$  space to table values

## For sphere map sphere surface to (u,v)

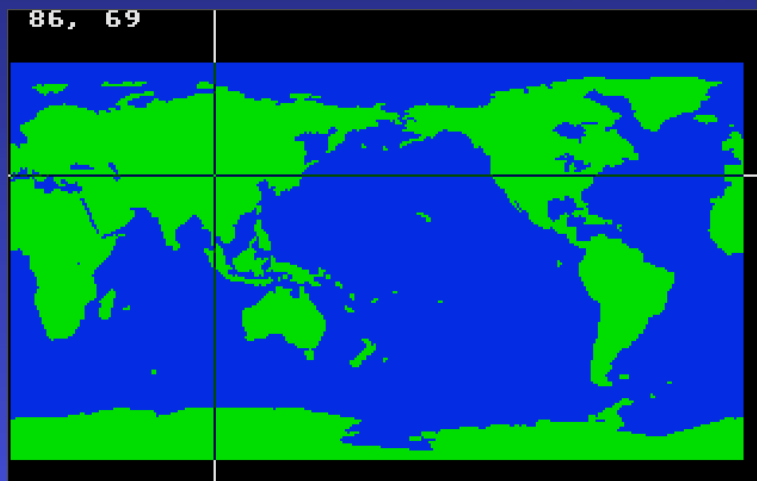


$$s = \frac{\tan^{-1}(z/x)}{\pi/2}$$
$$\text{if } (x > 0) \{ u = (1+s)/4 \}$$
$$\text{else } \{ u = 1/2 + (1-s)/4 \}$$

$$t = \frac{\tan^{-1}(y/x)}{\pi/2}$$
$$v = \frac{t+1}{2}$$

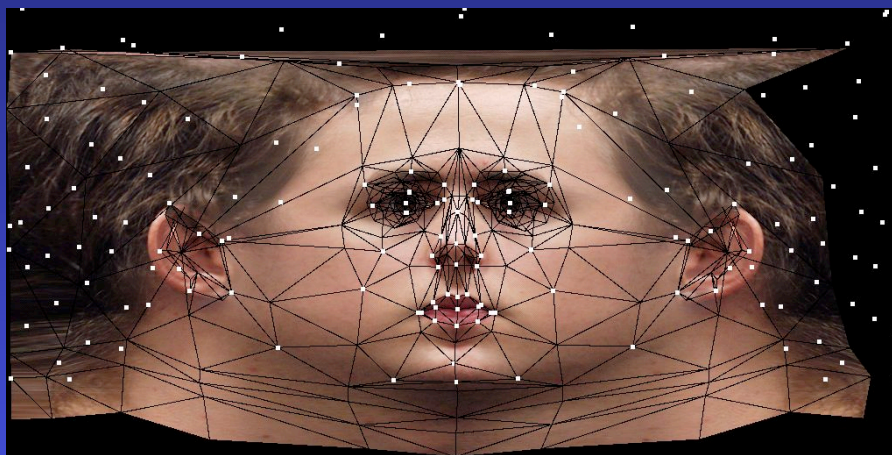
BUT -  
Has a seam  
& distorts

## Spherical - e.g., Cartography

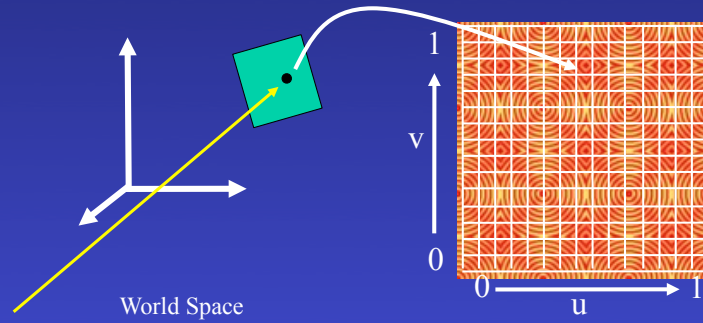




# Cylindrical Mapping

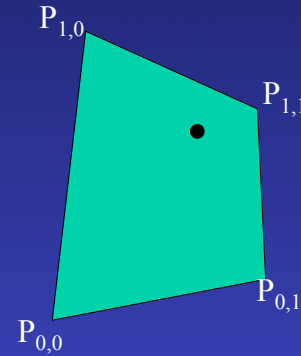


## For quadrilateral Texture Map Coordinates



Map  $(x,y,z)$  to  $u,v$  space to table values

## World space point to u,v space



$$P_{u,0} = P_{0,0} + u(P_{1,0} - P_{0,0})$$

$$P_{u,1} = P_{0,1} + u(P_{1,1} - P_{0,1})$$

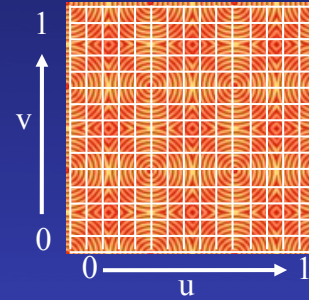
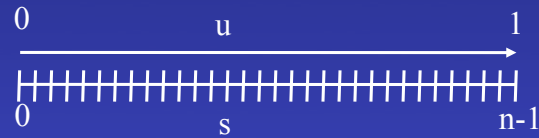
$$P_{u,v} = P_{u,0} + v(P_{u,1} - P_{u,0})$$

$$P_{u,v} = P_{0,0} + u(P_{1,0} - P_{0,0}) + v(P_{0,1} + u(P_{1,1} - P_{0,1}) - P_{0,0} + u(P_{1,0} - P_{0,0}))$$

$$P_{u,v} = P_{0,0} + u(P_{1,0} - P_{0,0}) + v(P_{0,1} - P_{0,0}) + uv(P_{1,1} - P_{0,1} + P_{1,0} - P_{0,0})$$

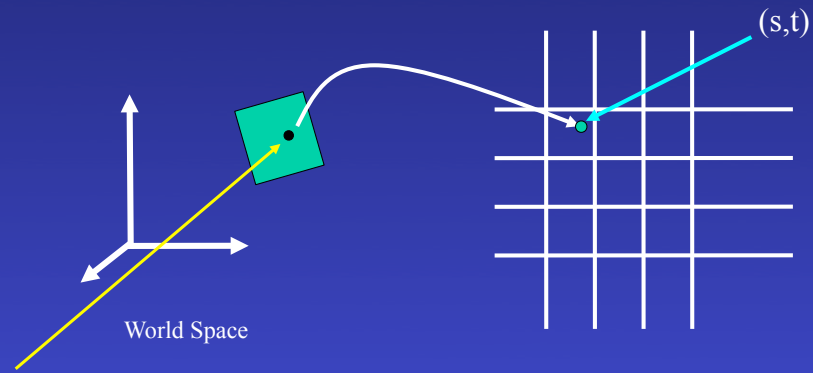
$$u = \frac{P_{u,v} - P_{0,0} - v(P_{0,1} - P_{0,0})}{(P_{1,0} - P_{0,0}) + v(P_{1,1} - P_{0,1} + P_{1,0} - P_{0,0})}$$

# u,v space to table indice space



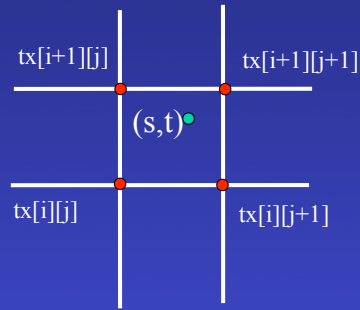
$$s = u(n-1)$$
$$t = m-1-v(m-1)$$

## A closer look



Values only at the intersections  
What value to use at non-intersection point?

# Closer still

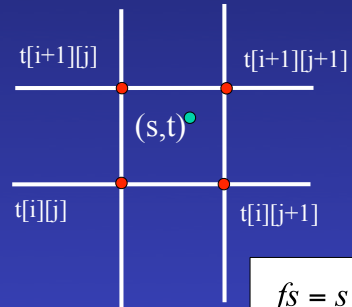


Use closest value?

$$i = \lfloor s + 0.5 \rfloor$$
$$j = \lfloor t + 0.5 \rfloor$$

$$txst = tx[i][j]$$

## Closer still



Interpolate 4 closest?

$$i = \lfloor s \rfloor$$
$$j = \lfloor t \rfloor$$

$$fs = s - \lfloor s \rfloor$$

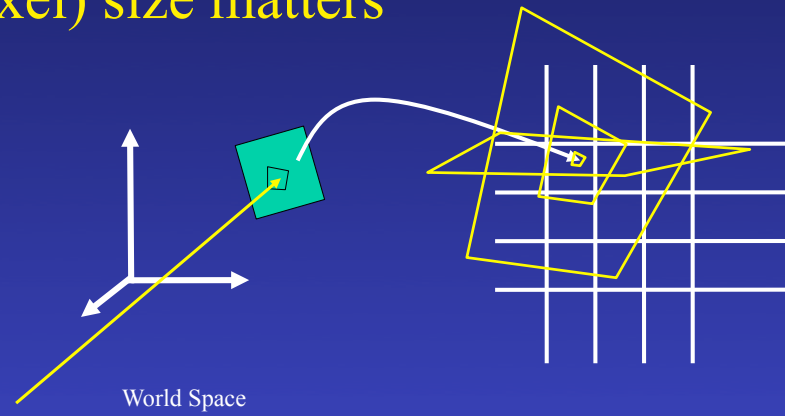
$$ft = t - \lfloor t \rfloor$$

$$ts1 = tx[i][j] + fs(tx[i+1][j] - tx[i][j])$$

$$ts2 = tx[i][j+1] + fs(tx[i+1][j+1] - tx[i][j+1])$$

$$txst = ts1 + ft(ts2 - ts1)$$

## (Pixel) size matters

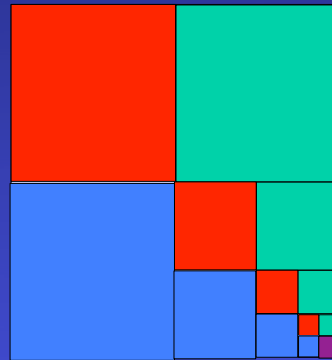


Can't just use pixel center and expect good results in all cases - need to consider how entire pixel maps into texture space



# One solution: Mip-mapping

Pre-filter texture, reducing resolution  
(increase size of grid relative to pixel size)



Successive table of values  
(r,g,b) at reduced resolution

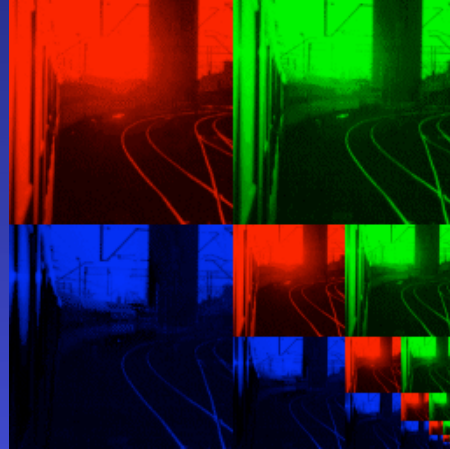
Down to single pixel

Index into highest resolution  
one in which bilinear  
interpolation makes sense

CSE 681

What size 'makes sense'? Pixel size is less than grid

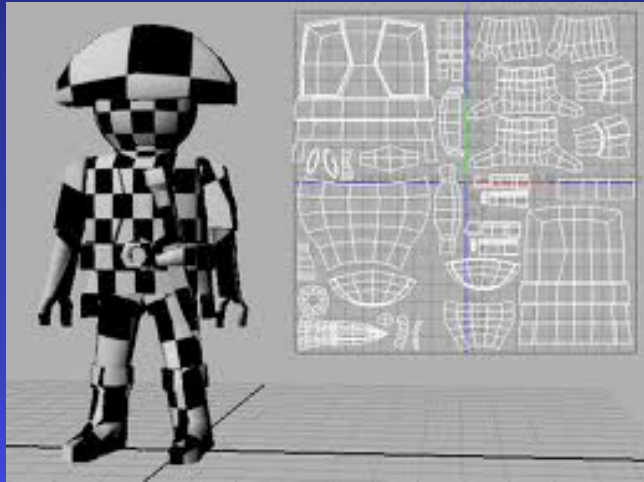
# One solution: Mip-mapping



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What size 'makes sense'? Pixel size is less than grid

# UV Mapping



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What size 'makes sense'? Pixel size is less than grid